

L22 Linear model: Regression and one-way ANOVA

1. Linear model

(1) Linear function

$y = f(x)$ is a linear function if $f(\alpha u + \beta v) = \alpha f(u) + \beta f(v)$.

If $y \in R^m$ and $x \in R^n$, then

$y = f(x)$ is a linear function $\iff \exists A \in R^{m \times n}$ such that $y = f(x) = Ax$.

Pf: $\Leftarrow$: $f(\alpha u + \beta v) = A(\alpha u + \beta v) = \alpha Au + \beta Av = \alpha f(u) + \beta f(v)$.

$\Rightarrow$: Let $A_i = f(e_i) \in R^m$ where $e_i \in R^n$ is the i th column of I_n , $i = 1, \dots, n$.

$$\begin{aligned} \text{Then } f(x) &= f(x_1 e_1 + \dots + x_n e_n) = x_1 f(e_1) + \dots + x_n f(e_n) \\ &= x_1 A_1 + \dots + x_n A_n = Ax. \end{aligned}$$

(2) Linear model

If in a model for random variable y , $E(y)$ is a linear function of unknown parameter vector $\beta \in R^p$, then this model is called a linear model. So a linear model for y with parameter vector $\beta \in R^p$ is

$$y = (m_1, \dots, m_p)\beta + \epsilon \text{ with } E(\epsilon) = 0.$$

(3) Samples from a linear model

Suppose $y_1, \dots, y_n$ is a random sample from the above linear model where y_i is observed

when $(m_1, \dots, m_p) = (m_{i1}, \dots, m_{in})$. Let $Y = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}$, $M = \begin{pmatrix} m_{11} & \dots & m_{1p} \\ \vdots & \ddots & \vdots \\ m_{n1} & \dots & m_{np} \end{pmatrix}$. Then

$Y = M\beta + \epsilon$ with $E(\epsilon) = 0 \in R^n$ characterizes a linear model based on sample.

Comments: Statistical inference is based on sample $Y = M\beta + \epsilon$.

$E(Y) = M\beta \in L(M)$, a linear space in R^n .

Matrix M characterizes the model, i.e., different M gives different models.

2. Linear regression model is a linear model

(1) Regression model

Linear regression $y = \beta_0 + \beta_1 x_1 + \dots + \beta_{p-1} x_{p-1} + \epsilon$ with $E(\epsilon) = 0$ is a linear model where

$$E(y) = \beta_0 + \beta_1 x_1 + \dots + \beta_{p-1} x_{p-1} = (1, x_1, \dots, x_{p-1})\beta \text{ with } \beta = \begin{pmatrix} \beta_0 \\ \vdots \\ \beta_{p-1} \end{pmatrix}$$

is called the regression function.

Comments: Regression model represents infinite number of populations,

Caution: $E(y)$ is a function of $(1, x_1, \dots, x_p)$ and is also a function of $\beta \in R^p$.

(2) Samples from a regression model

Suppose y_i is observed when $(1, x_1, \dots, x_{p-1})$ is $(1, x_{i1}, \dots, x_{ip-1})$, $i = 1, \dots, n$.

Let $Y = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix} \in R^n$, $X = \begin{pmatrix} 1 & x_{11} & \dots & x_{1p-1} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & x_{n1} & \dots & x_{np-1} \end{pmatrix} \in R^{n \times p}$ and $\epsilon = \begin{pmatrix} \epsilon_1 \\ \vdots \\ \epsilon_n \end{pmatrix}$ with $E(\epsilon) = 0_n$. Then $Y = X\beta + \epsilon$. So $E(Y) = X\beta$ lies in $\mathcal{R}(X)$, a linear space in R^n .

3. One-way ANOVA is a linear model

(1) One-way ANOVA model

In an experiment response y is affected by p levels of a single factor.

Suppose under the i th level, called the i th treatment, $E(y) = \mu_i$.

Let d_i be the indicator for the i th treatment, i.e., $d_i = \begin{cases} 1 & \text{ith treatment is applied} \\ 0 & \text{otherwise} \end{cases}$

and $\mu = \begin{pmatrix} \mu_1 \\ \vdots \\ \mu_p \end{pmatrix}$. The one-way ANOVA below is a linear model.

$$y = d_1\mu_1 + \cdots + d_p\mu_p + \epsilon = (d_1, \dots, d_p)\mu + \epsilon \text{ with } E(\epsilon) = 0.$$

Comments: This model represents p populations since $(d_1, \dots, d_p)$ with one $d_i = 1$ and rest $d_j = 0$ has p different values and $(d_1, \dots, d_p)\mu$ has p values: $\mu_1, \dots, \mu_p$.

(2) Samples from one-way ANOVA

Suppose y_i is observed on an experiment unit when $(d_1, \dots, d_p) = (d_{i1}, \dots, d_{ip})$, $i = 1, \dots, n$.

Let $Y = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix} \in R^n$, $D = \begin{pmatrix} d_{11} & \cdots & d_{1p} \\ \vdots & \ddots & \vdots \\ d_{n1} & \cdots & d_{np} \end{pmatrix} \in R^{n \times p}$ and $\epsilon = \begin{pmatrix} \epsilon_1 \\ \vdots \\ \epsilon_n \end{pmatrix}$ with $E(\epsilon) = 0$.

Then $Y = D\mu + \epsilon$. So $E(Y) = D\mu \in L(D) = R^p$.

Comment: Matrix D specifies how many and which experiment units are subject to which treatment. Hence it is called the design matrix.

Ex1: $D = \begin{pmatrix} 1_{n_1} & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & 1_{n_p} \end{pmatrix}$ is often denoted by J .

(3) Reparameterization

Let $\mu_{\cdot} = \frac{\mu_1 + \cdots + \mu_p}{p} = \frac{1'_p}{p}\mu = 1_p^+\mu$, $\alpha_i = \mu_i - \mu_{\cdot}$ and $\alpha = \begin{pmatrix} \alpha_1 \\ \vdots \\ \alpha_p \end{pmatrix} = (I_p - 1_p 1_p^+)\mu$. Then

$$\theta = \begin{pmatrix} \mu_{\cdot} \\ \alpha \end{pmatrix} = \begin{pmatrix} 1_p^+ \\ I_p - 1_p 1_p^+ \end{pmatrix} \mu = (1_p, I_p - 1_p 1_p^+)^+ \mu \in R^{p+1} \text{ and } \mu = (1_p, I_p)\theta \in R^p.$$

Here $\alpha_1, \dots, \alpha_p$ are called the factor effects. Clearly $\mu_i = \mu_j \iff \alpha_i = \alpha_j$.

When using θ there is a restriction $\alpha_1 + \cdots + \alpha_p = 0 \iff (0, 1'_p)\theta = 0$.

(4) A model with restriction

By the reparameterization in (3), for data vector Y

$$Y = J\mu + \epsilon \text{ with } E(\epsilon) = 0 \iff Y = J(1_p, I_p)\theta + \epsilon \text{ with } E(\epsilon) = 0 \\ \text{under the restriction } (0, 1'_p)\theta = 0.$$

Ex2: $(0, 1'_p)\theta = 0 \iff \theta \in \mathcal{N}((0, 1'_p))$. So

$$\begin{aligned} E(Y) = J(1_p, I_p)\theta &\in J(1_p, I_p)\mathcal{N}((0, 1'_p)) = J(1_p, I_p)\mathcal{N}\left(\begin{pmatrix} 0 & 0 \\ 0 & 1_p 1_p^+ \end{pmatrix}\right) \\ &= J(1_p, I_p)\mathcal{R}\left(\begin{pmatrix} 1 & 0 \\ 0 & I_p - 1_p 1_p^+ \end{pmatrix}\right) = J\mathcal{R}((1_p, I_p - 1_p 1_p^+)) \\ &= J\mathcal{R}(I_p) = \mathcal{R}(J). \end{aligned}$$