

L04: Population parameter

1. Population mean vector

(1) Population mean vector

The mean vector for population $\mathbf{x} = \begin{pmatrix} X_1 \\ \vdots \\ X_p \end{pmatrix}$ is $\mu = E(\mathbf{x}) = \begin{pmatrix} E(X_1) \\ \vdots \\ E(X_p) \end{pmatrix} = \begin{pmatrix} \mu_1 \\ \vdots \\ \mu_p \end{pmatrix}$ where

$$\mu_i = E(X_i) = \int_R x_i f_i(x_i) dx_i = \iiint_{R^p} x_i f(x_1, \dots, x_p) dx_1, \dots, dx_p$$

is the average value of X_i . $\mu = E(\mathbf{x})$ is the average value of $\mathbf{x}$. Since

$$\mu \text{ exists} \iff \mu_i \text{ exists for all } i \iff f_i(x_i) \text{ exists for all } i \iff f(x_1, \dots, x_p) \text{ exists}$$

there are cases where $\mathbf{x}$ does not have joint pdf but $E(\mathbf{x})$ exists.

(2) Expectation of random matrix

For random matrix $\mathbf{Z} = (Z_{ij})_{a \times b}$, the expectation $E(\mathbf{Z}) = (E(Z_{ij}))_{a \times b}$. To have $E(\mathbf{Z})$ we have to

assume that the distributions of Z_{ij} are known for all i and j . If $\mathbf{x} = \begin{pmatrix} X_1 \\ \vdots \\ X_p \end{pmatrix}$ has joint pdf $f(\mathbf{x})$

and $Z_{ij} = g_{ij}(\mathbf{x})$, then $E(Z_{ij}) = \iint_{R^p} g_{ij}(\mathbf{x}) f(\mathbf{x}) dx_1, \dots, dx_p$.

(3) A formula for expectation

Let X, Y, U, V be random matrices. $E(AXB + CYD + \alpha) = A[E(X)]B + C[E(Y)]D + \alpha$.

Ex1: $\mathbf{x} = \begin{pmatrix} X_1 \\ \vdots \\ X_p \end{pmatrix}$ has joint pdf $f(\mathbf{x})$. Then $E(\mathbf{x}\mathbf{x}') = E[(X_i X_j)_{p \times p}] = (E(X_i X_j))_{p \times p}$ where

$$E(X_i X_j) = \iint_{R^2} x_i x_j f_{ij}(x_i, x_j) dx_i dx_j = \iint_{R^p} x_i x_j f(\mathbf{x}) dx_1, \dots, dx_p.$$

$E(\mathbf{x}\mathbf{x}')$ exists if the marginal distributions for X_i and X_j are known for all (i, j) .

2. Population variance-covariance matrix

(1) Population variance-covariance matrix

The variance-covariance matrix for population $\mathbf{x} = \begin{pmatrix} X_1 \\ \vdots \\ X_p \end{pmatrix}$ is

$$\Sigma = \begin{pmatrix} \text{var}(X_1) & \cdots & \text{cov}(X_1, X_p) \\ \vdots & \ddots & \vdots \\ \text{cov}(X_p, X_1) & \cdots & \text{var}(X_p) \end{pmatrix} = \begin{pmatrix} \sigma_{11} & \cdots & \sigma_{1p} \\ \vdots & \ddots & \vdots \\ \sigma_{p1} & \cdots & \sigma_{pp} \end{pmatrix} = \begin{pmatrix} \sigma_1^2 & \cdots & \sigma_{1p} \\ \vdots & \ddots & \vdots \\ \sigma_{p1} & \cdots & \sigma_p^2 \end{pmatrix}.$$

With $\sigma_{ij} = \text{cov}(X_i, X_j) = E[(X_i - \mu_i)(X_j - \mu_j)] = E(X_i X_j) - \mu_i \mu_j$,

$$\Sigma = E[(\mathbf{x} - \mu)(\mathbf{x} - \mu)'] = E(\mathbf{x}\mathbf{x}') - \mu\mu'.$$

We often write $\mathbf{x} \sim (\mu, \Sigma)$ to indicate $E(\mathbf{x}) = \mu$ and $\text{Cov}(X) = \Sigma$.

(2) Covariance matrix

The covariance matrix for random vector $\mathbf{x} \in R^p$ and random vector $\mathbf{y} \in R^q$ is

$$\Sigma_{xy} = \begin{pmatrix} \text{cov}(x_1, y_1) & \cdots & \text{cov}(x_1, y_q) \\ \vdots & \ddots & \vdots \\ \text{cov}(x_p, y_1) & \cdots & \text{cov}(x_p, y_q) \end{pmatrix} \in R^{p \times q}.$$

With $\text{cov}(X_i, Y_j) = E[(X_i - \mu_{x_i})(Y_j - \mu_{y_j})] = E(X_i Y_j) - \mu_{x_i} \mu_{y_j}$,

$$\text{Cov}(\mathbf{x}, \mathbf{y}) = E[(\mathbf{x} - \mu_x)(\mathbf{y} - \mu_y)'] = E(\mathbf{x}\mathbf{y}') - \mu_x \mu_y'.$$

Clearly $\text{Cov}(\mathbf{x}) = \text{Cov}(\mathbf{x}, \mathbf{x})$ and $\text{Cov}(\mathbf{y}, \mathbf{x}) = [\text{Cov}(\mathbf{x}, \mathbf{y})]'$.

- (3) A formula for covariance matrix

Let $\mathbf{x}, \mathbf{y}, \mathbf{u}$ and $\mathbf{v}$ be random vectors. Then

$$\begin{aligned} & \text{Cov}(A\mathbf{x} + B\mathbf{y} + \alpha, C\mathbf{u} + D\mathbf{v} + \beta) \\ &= A \text{cov}(\mathbf{x}, \mathbf{u})C' + A \text{Cov}(\mathbf{x}, \mathbf{v})D' + B \text{Cov}(\mathbf{y}, \mathbf{u})C' + B \text{Cov}(\mathbf{y}, \mathbf{v})D' \end{aligned}$$

Ex2: $\begin{pmatrix} \mathbf{x} \\ \mathbf{y} \end{pmatrix} \sim (\mu, \Sigma)$ where $\mu = \begin{pmatrix} \mu_1 \\ \mu_2 \end{pmatrix}$ and $\Sigma = \begin{pmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{pmatrix}$. Let $\mathbf{z} = A \begin{pmatrix} \mathbf{x} \\ \mathbf{y} \end{pmatrix}$ with $A = \begin{pmatrix} I & 0 \\ -\Sigma_{21}\Sigma_{11}^{-1} & I \end{pmatrix}$. Then $\mathbf{z} \sim \left(\begin{pmatrix} \mu_1 \\ \mu_2 - \Sigma_{21}\Sigma_{11}^{-1}\mu_1 \end{pmatrix}, \begin{pmatrix} \Sigma_{11} & 0 \\ 0 & \Sigma_{22.1} \end{pmatrix} \right)$.

3. Population correlation matrix

- (1) Population correlation matrix

Let Σ be the variance-covariance matrix for the population $\mathbf{x} = \begin{pmatrix} X_1 \\ \vdots \\ X_p \end{pmatrix}$.

Then $\Delta^2 = \text{diag}(\Sigma) = \text{diag}(\sigma_1^2, \dots, \sigma_p^2)$ is the population variance matrix and $\Delta = \text{diag}(\sigma_1, \dots, \sigma_p)$ is the population standard deviation matrix.

$$\rho = \Delta^{-1}\Sigma\Delta^{-1} = \begin{pmatrix} \frac{\sigma_1^2}{\sigma_1\sigma_1} & \cdots & \frac{\sigma_{1p}}{\sigma_1\sigma_p} \\ \vdots & \ddots & \vdots \\ \frac{\sigma_{p1}}{\sigma_p\sigma_1} & \cdots & \frac{\sigma_p^2}{\sigma_p\sigma_p} \end{pmatrix} = \begin{pmatrix} 1 & \cdots & \rho_{1p} \\ \vdots & \ddots & \vdots \\ \rho_{p1} & \cdots & 1 \end{pmatrix}$$

is the population correlation matrix.

- (2) Properties

$$-1 \leq \rho_{ij} = \frac{\sigma_{ij}}{\sigma_i\sigma_j} \leq 1$$

$$\rho_{ij} = 1 \iff X_i = aX_j + b \text{ with } a > 0 \text{ and } \rho_{ij} = -1 \iff X_i = aX_j + b \text{ with } a < 0.$$

4. Parameters for conditional distributions

- (1) Conditional mean vector

Conditional pdf of $\mathbf{y} \in R^q$ given $\mathbf{x} \in R^p$ is $f(\mathbf{y}|\mathbf{x})$. Then the conditional mean of $\mathbf{y}$ given $\mathbf{x}$

$$E(\mathbf{y}|\mathbf{x}) = \begin{pmatrix} E(y_1|\mathbf{x}) \\ \vdots \\ E(y_q|\mathbf{x}) \end{pmatrix} \text{ is vector valued function of } \mathbf{x}$$

where $E(y_j|\mathbf{x}) = \int_R y_j f(\mathbf{y}|\mathbf{x}) dy_1, \dots, dy_q$ is a function of $\mathbf{x}$.

- (2) Conditional variance-covariance matrix

The conditional variance-covariance matrix of $\mathbf{y}$ given $\mathbf{x}$

$$\text{Cov}(\mathbf{y}|\mathbf{x}) = E\{[\mathbf{y} - E(\mathbf{y}|\mathbf{x})][\mathbf{y} - E(\mathbf{y}|\mathbf{x})]'\} = E(\mathbf{y}\mathbf{y}'|\mathbf{x}) - [E(\mathbf{y}|\mathbf{x})][E(\mathbf{y}|\mathbf{x})]'$$

is a matrix-valued function of $\mathbf{x}$.

L05: Normal distributions

1. Parameters of conditional distributions

(1) Expectation of conditional expectations

$\mathbf{x} \in R^p$, $\mathbf{y} \in R^q$ and $\mathbf{Z} = (g_{ij}(\mathbf{y}))_{a \times b}$. Conditional expectation $E(\mathbf{Z}|\mathbf{x}) = (E(g_{ij}(\mathbf{y})|\mathbf{x}))_{a \times b}$ is a matrix-valued function of $\mathbf{x}$. Then $E[E(\mathbf{Z}|\mathbf{x})] = E(\mathbf{Z})$.

Proof We show $E[E(g_{ij}(\mathbf{y})|\mathbf{x})] = E(g_{ij}(\mathbf{y})) = E(\mathbf{Z}_{ij})$.

$$\begin{aligned} E[E(g_{ij}(\mathbf{y})|\mathbf{x})] &= \iint_{R^p} E(g_{ij}(\mathbf{y})|\mathbf{x}) f_x(\mathbf{x}) dx_1, \dots, dx_p \\ &= \iint_{R^p} \left[\iint_{R^q} g_{ij}(\mathbf{y}) f(\mathbf{y}|\mathbf{x}) dy_1, \dots, dy_q \right] f_x(\mathbf{x}) dx_1, \dots, dx_p \\ &= \iint_{R^{p+q}} g_{ij}(\mathbf{y}) f(\mathbf{x}, \mathbf{y}) dx_1, \dots, dx_p dy_1, \dots, dy_q = E(g_{ij}(\mathbf{y})) = E(\mathbf{Z}_{ij}). \end{aligned}$$

(2) $\text{Cov}(\mathbf{y}) = E[\text{Cov}(\mathbf{y}|\mathbf{x})] + \text{Cov}(E(\mathbf{y}|\mathbf{x}))$.

Proof Note that

$$\begin{aligned} E[\text{Cov}(\mathbf{y}|\mathbf{x})] &= E\{E(\mathbf{y}\mathbf{y}'|\mathbf{x}) - [E(\mathbf{y}|\mathbf{x})][E(\mathbf{y}|\mathbf{x})]'\} \\ &= E(\mathbf{y}\mathbf{y}') - E\{[E(\mathbf{y}|\mathbf{x})][E(\mathbf{y}|\mathbf{x})]'\}. \\ \text{Cov}[E(\mathbf{y}|\mathbf{x})] &= E\{[E(\mathbf{y}|\mathbf{x})][E(\mathbf{y}|\mathbf{x})]'\} - \{E[E(\mathbf{y}|\mathbf{x})]\}\{E[E(\mathbf{y}|\mathbf{x})]\}' \\ &= E\{[E(\mathbf{y}|\mathbf{x})][E(\mathbf{y}|\mathbf{x})]'\} - [E(\mathbf{y})][E(\mathbf{y})]'. \end{aligned}$$

Thus $\text{Cov}[E(\mathbf{y}|\mathbf{x})] + E[\text{Cov}(\mathbf{y}|\mathbf{x})] = E(\mathbf{y}\mathbf{y}') - [E(\mathbf{y})][E(\mathbf{y})]' = \text{Cov}(\mathbf{y})$.

Comment: $g(\mathbf{x}) = E(\mathbf{y}|\mathbf{x})$ is a function of $\mathbf{x}$. $E(g(\mathbf{x})) = E(\mathbf{y})$. $\text{Cov}(g(\mathbf{x})) \leq \text{Cov}(\mathbf{y})$.

(3) Independence and parameters

$$\begin{aligned} \mathbf{x} \in R^p \text{ and } \mathbf{y} \in R^q \text{ are indep.} &\stackrel{\text{def}}{\iff} f(\mathbf{x}, \mathbf{y}) = f_x(\mathbf{x}) f_y(\mathbf{y}) \\ &\stackrel{*}{\implies} E(\mathbf{x}\mathbf{y}') = E(\mathbf{x})[E(\mathbf{y})]' \stackrel{**}{\iff} \text{Cov}(\mathbf{x}, \mathbf{y}) = 0 \\ &\stackrel{\text{def}}{\iff} \mathbf{x} \text{ and } \mathbf{y} \text{ are uncorrelated} \end{aligned}$$

$\stackrel{*}{\implies}$: With $E(\mathbf{x}\mathbf{y}') = (E(X_i Y_j))_{p \times q}$ and $E(\mathbf{x})[E(\mathbf{y})]' = (E(X_i) E(Y_j))_{p \times q}$ we show $E(X_i Y_j) = E(X_i) E(Y_j)$.

$$\begin{aligned} E(X_i Y_j) &= \iint_{R^{p+q}} x_i y_j f(\mathbf{x}, \mathbf{y}) dx_1, \dots, dx_p dy_1, \dots, dy_q \\ &= \iint_{R^p} x_i f_x(\mathbf{x}) dx_1, \dots, dx_p \iint_{R^q} y_j f_y(\mathbf{y}) dy_1, \dots, dy_q = E(X_i) E(Y_j) \end{aligned}$$

$\stackrel{**}{\iff}$: Since $\text{Cov}(\mathbf{x}, \mathbf{y}) = E(\mathbf{x}\mathbf{y}') - E(\mathbf{x})[E(\mathbf{y})]'$, $\text{Cov}(\mathbf{x}, \mathbf{y}) = 0$ and $E(\mathbf{x}\mathbf{y}') = E(\mathbf{x})[E(\mathbf{y})]'$ are equivalent.

2. Multivariate normal distributions

(1) Definition of normal distributions

With $\mu \in R^p$ and positive definite $\Sigma \in R^{p \times p}$, let

$$f(x; \mu, \Sigma) = \frac{1}{(2\pi)^{p/2} |\Sigma|^{1/2}} \exp \left[-\frac{1}{2} (x - \mu)' \Sigma^{-1} (x - \mu) \right].$$

Then $f(\mathbf{x}; \mu, \Sigma) > 0$ and by the substitution of $z = \Sigma^{-1/2}(x - \mu) \iff x = \Sigma^{1/2}z + \mu$ with $J = \frac{\partial(x_1, \dots, x_p)}{\partial(z_1, \dots, z_p)} = \Sigma^{1/2}$.

$$\iint_{R^p} f(x) dx_1, \dots, dx_p = \iint_{R^p} \frac{1}{(2\pi)^{p/2}} \exp \left(-\frac{1}{2} z' z \right) dz_1, \dots, dz_p = \prod_{i=1}^p \int_R \frac{1}{\sqrt{2\pi}} e^{-\frac{z_i^2}{2}} dz_i = 1$$

So $f(\mathbf{x}; \mu, \Sigma)$ is a pdf. The distribution of $\mathbf{x} \in R^p$ with pdf $f(\mathbf{x}; \mu, \Sigma)$ is called a normal distribution denoted by $\mathbf{x} \sim N(\mu, \Sigma)$.

- (2) Parameters of $N(\mu, \Sigma)$

Calculation shows $\mathbf{x} \sim N(\mu, \Sigma) \implies \mathbf{x} \sim (\mu, \Sigma)$.

- (3) Transformation

If $\mathbf{x} \sim N(\mu, \Sigma)$ and $A \in R^{q \times p}$ has full row rank, then $\mathbf{y} = A\mathbf{x} + b \sim N(A\mu + b, A\Sigma A')$

Proof Skipped. **Comment:** Recall $\mathbf{x} \sim (\mu, \Sigma) \implies A\mathbf{x} + b \sim (A\mu + b, A\Sigma A')$.

3. Marginal distributions and conditional distributions

- (1) Marginal distributions

By the transformation one can easily see that the marginal distributions of a normal distribution are normal distributions.

Ex1: $\mathbf{x} = \begin{pmatrix} X_1 \\ X_2 \\ X_3 \end{pmatrix} \sim N \left(\begin{pmatrix} \mu_1 \\ \mu_2 \\ \mu_3 \end{pmatrix}, \begin{pmatrix} \sigma_1^2 & \sigma_{12} & \sigma_{13} \\ \sigma_{21} & \sigma_2^2 & \sigma_{23} \\ \sigma_{31} & \sigma_{32} & \sigma_3^2 \end{pmatrix} \right).$

Then $X_2 = (0, 1, 0)\mathbf{x} \sim N(\mu_2, \sigma_2^2)$ and

$$\begin{pmatrix} X_1 \\ X_3 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \mathbf{x} \sim N \left(\begin{pmatrix} \mu_1 \\ \mu_3 \end{pmatrix}, \begin{pmatrix} \sigma_1^2 & \sigma_{13} \\ \sigma_{31} & \sigma_3^2 \end{pmatrix} \right).$$

- (2) Independence

Suppose $\begin{pmatrix} \mathbf{x} \\ \mathbf{y} \end{pmatrix} \sim N \left(\begin{pmatrix} \mu_x \\ \mu_y \end{pmatrix}, \begin{pmatrix} \Sigma_x & \Sigma_{xy} \\ \Sigma_{yx} & \Sigma_y \end{pmatrix} \right)$. Then

$$\mathbf{x} \text{ and } \mathbf{y} \text{ are indep.} \iff \Sigma_{xy} = 0 \text{ and } \Sigma_{yx} = 0.$$

Proof Only give a sketch.

$\implies$: $\mathbf{x}$ and $\mathbf{y}$ are indep $\implies \mathbf{x}$ and $\mathbf{y}$ are uncorrelated.

$\impliedby$: $f(\mathbf{x}, \mathbf{y}) = f_x(\mathbf{x}) f_y(\mathbf{y})$.

- (3) Conditional distributions

Suppose $\begin{pmatrix} \mathbf{x} \\ \mathbf{y} \end{pmatrix} \sim N \left(\begin{pmatrix} \mu_1 \\ \mu_2 \end{pmatrix}, \begin{pmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{pmatrix} \right)$.

Let $\Sigma_{11.2} = \Sigma_{11} - \Sigma_{12}\Sigma_{22}^{-1}\Sigma_{21}$ and $\Sigma_{22.1} = \Sigma_{22} - \Sigma_{21}\Sigma_{11}^{-1}\Sigma_{12}$.

Then $\mathbf{x} | \mathbf{y} \sim N(\mu_1 + \Sigma_{12}\Sigma_{22}^{-1}(\mathbf{y} - \mu_2), \Sigma_{11.2})$ and

$\mathbf{y} | \mathbf{x} \sim N(\mu_2 + \Sigma_{21}\Sigma_{11}^{-1}(\mathbf{x} - \mu_1), \Sigma_{22.1})$.

Proof Only show the second one.

$$\begin{aligned} \begin{pmatrix} \mathbf{z}_1 \\ \mathbf{z}_2 \end{pmatrix} &= \begin{pmatrix} I & 0 \\ -\Sigma_{21}\Sigma_{11}^{-1} & I \end{pmatrix} \begin{pmatrix} \mathbf{x} \\ \mathbf{y} \end{pmatrix} = \begin{pmatrix} \mathbf{x} \\ \mathbf{y} - \Sigma_{21}\Sigma_{11}^{-1}\mathbf{x} \end{pmatrix} \\ &\sim N \left(\begin{pmatrix} \mu_1 \\ \mu_2 - \Sigma_{21}\Sigma_{11}^{-1}\mu_1 \end{pmatrix}, \begin{pmatrix} \Sigma_{11} & 0 \\ 0 & \Sigma_{22.1} \end{pmatrix} \right). \end{aligned}$$

So $\mathbf{z}_1 = \mathbf{x} \sim N(\mu_1, \Sigma_{11})$ and $\mathbf{z}_2 = \mathbf{y} - \Sigma_{21}\Sigma_{11}^{-1}\mathbf{x} \sim N(\mu_2 - \Sigma_{21}\Sigma_{11}^{-1}\mu_1, \Sigma_{22.1})$ are independent.

Thus $\mathbf{z}_2 | \mathbf{z}_1 \sim N(\mu_2 - \Sigma_{21}\Sigma_{11}^{-1}\mu_1, \Sigma_{22.1})$.

Therefore $\mathbf{z}_2 + \Sigma_{21}\Sigma_{11}^{-1}\mathbf{z}_1 | \mathbf{z}_1 \sim N(\mu_2 + \Sigma_{21}\Sigma_{11}^{-1}(\mathbf{z}_1 - \mu_1), \Sigma_{22.1})$, i.e.,

$$\mathbf{y} | \mathbf{x} \sim N(\mu_2 + \Sigma_{21}\Sigma_{11}^{-1}(\mathbf{x} - \mu_1), \Sigma_{22.1}).$$