

Let V be a vector space of dimension n . The tensor algebra of V is $T(V)$, the graded algebra of all k -fold tensor products of V , $k = 0, \dots, \infty$.

$$T(V) = \bigoplus_{k=0}^{\infty} V^k$$

where $V^k = \underbrace{V \oplus \dots \oplus V}_k$ and $V^0 = \mathbb{K}$, the underlying field.

Let I be the two-sided ideal consisting of elements xx . The exterior algebra of V is

$$\Lambda(V) = T(V)/I.$$

The exterior algebra inherits the grading of T w/

$$\Lambda^0(V) = \mathbb{K}$$

$$\Lambda^1(V) = V \quad \text{and}$$

$$\Lambda^k(V) = 0 \quad \text{for } k > n.$$

In fact, $\dim(\Lambda^k(V)) = \binom{n}{k}$, so that $\Lambda^n(V) = \mathbb{K}$ as well.

We are interested in the case where M is a (real) smooth manifold of dimension n and V is a model cotangent space. We can create the external algebra bundle $\Lambda(T^*M) \rightarrow M$. (RE write out the details.)

Defn. A differential k -form on M is a smooth section of $\Lambda^k(T^*M) \rightarrow M$. We denote the space of all smooth k -forms on M by $\Omega^k(M) = \Omega^k$ if M is clear from context.

If $(x^1, \dots, x^n)$ are local coordinates on M , then a differential form is an object of the form

$$w = \sum_{1 \leq i_1 < \dots < i_j \leq n} w_{i_1 \dots i_j} dx^{i_1} \wedge \dots \wedge dx^{i_j}$$

j is called the degree of w . Here $\wedge$ is the alternating product: $dx^i \wedge dx^k = \begin{cases} 0 & \text{if } i=k \\ -dx^k \wedge dx^i & \text{if } i \neq k \end{cases}$

The exterior derivative of w is the form of degree $j+1$ defined by

$$dw := \sum_{i_0=1, \dots, n} \sum_{1 \leq i_1 < \dots < i_j \leq n} \frac{\partial}{\partial x^{i_0}} w_{i_1 \dots i_j} dx^{i_0} \wedge dx^{i_1} \wedge \dots \wedge dx^{i_j}$$

$$d^2 = 0.$$

A differential form w is said to be closed if $dw = 0$, and exact if there exists a form α (of degree $j-1$) such that $w = d\alpha$.

Clearly, every exact form is closed.

Defn. The j^{th} de Rham cohomology group of M is

$$H^j(M; \mathbb{R}) = \frac{\{\text{closed } j\text{-forms}\}}{\{\text{exact } j\text{-forms}\}}$$

Here " j -form" means differential form of degree j .

We consider equivalence classes of degree j , where two closed forms w_1 and w_2 are equivalent iff there exists a $(j-1)$ form α such that $w_2 - w_1 = d\alpha$. equivalence classes

Thus $H^j(M; \mathbb{R})$ consists of ~~the~~ closed j -forms that differ only by an exact j -form.

$H^j(M; \mathbb{R})$ is not only a group (under addition) but a real vector space.

d induces a morphism of groups $d: H^j(M; \mathbb{R}) \rightarrow H^{j+1}(M; \mathbb{R})$

We are interested in Riemann surfaces, so $n=2$. The only types of (real) differential forms are thus 0-forms (smooth functions), 1-forms (already studied), and 2-forms.

In local coordinates (x, y) a two form is represented by

$$\theta = \theta(x, y) dx \wedge dy \quad \text{for some } \theta \in \mathcal{F}(M) = \mathcal{O}(M).$$

As before, we put $dz = dx + i dy$ and $d\bar{z} = dx - i dy$ (locally).

$$\text{Then } dz \wedge d\bar{z} = -2i dx \wedge dy.$$

Now, suppose X is a surface, $[f] \in \mathcal{T}(X)$ a complex structure on X , and $S = f(X)$. Let $\lambda^2(z) d\bar{z} \wedge dz$ be a conformal Riemannian metric.

The fundamental two-form or Kähler form of the metric is

$$\omega := \lambda^2(z) dx \wedge dy = \frac{i}{2} \lambda^2(z) dz \wedge d\bar{z}.$$

We define an operation $*$ on forms as follows.

For a complex-valued function $f: S \rightarrow \mathbb{C}$,

$$\star f := f \omega \quad \text{or} \quad \star f(z) = f(z) \lambda^2(z) dz \wedge d\bar{z}$$

For a one-form $\alpha = f dx + g dy$

$$\star \alpha := -g dx + f dy$$

or in complex notation, if $\alpha = u dz + v d\bar{z}$,

$$\star \alpha = -iu dz + iv d\bar{z}.$$

For a 2-form $\eta = h(z) dx \wedge dy$,

$$\star \eta := \frac{1}{\lambda^2(z)} h(z).$$

Notice $\star$ interchanges 0 and 2 forms, and maps 1-forms to 1-forms. Clearly $\star$'s action on 1-forms does not depend on the choice of metric. The others, however, do.

We can define a scalar product on the vector space of k -forms by

$$(d_1, d_2) := \int_S \alpha_1 \wedge \star \bar{\alpha}_2,$$

and thus obtain a Hilbert space

$$A_k^2 := \{ k\text{-forms } \alpha \text{ w/ measurable coefficients and } \langle \alpha, \alpha \rangle < \infty \}.$$

If α is a 1-form, for example, then in local coords

$$\begin{aligned}\alpha \wedge \star \alpha &= i(u\bar{u} + v\bar{v}) dz \wedge d\bar{z} \\ &= 2(|u|^2 + |v|^2) dx \wedge dy\end{aligned}$$

so that the product is indeed positive definite. Further

$$(\alpha_1, \alpha_2) = \overline{\lambda}(\alpha_2, \alpha_1)$$

and

$$(\star \alpha_1, \star \alpha_2) = (\alpha_1, \alpha_2).$$

Thus, $\star$ is an isometry of A_k^2 into A_{2-k}^2 . It is also onto since $\star \star = (-1)^k$.

Further, if $\alpha_1 \in A_k^2$ and $\alpha_2 \in A_{k+1}^2$ are smooth and S is compact, then

$$\begin{aligned}(d\alpha_1, \alpha_2) &= \int_S d\alpha_1 \wedge \star \bar{\alpha}_2 \\ &= (-1)^{k+1} \int_S \alpha_1 \wedge d(\star \bar{\alpha}_2) + \int_S d(\alpha_1 \wedge \star \bar{\alpha}_2) \\ &= (-1)^{k+1} \int_S \alpha_1 \wedge d(\star \bar{\alpha}_2) \\ &= - \int_S \alpha_1 \wedge \star (\star d \star \bar{\alpha}_2) \\ &= -(\alpha_1, \star d \star \alpha_2)\end{aligned}$$

We set $d^\star = -\star d \star$ and see that it is the (formal) adjoint of d wrt $(\cdot, \cdot)$.

Note: Even for 1-forms, $d^\star$ depends on the choice of metric.

Now let f be a smooth ~~compactly supported~~ function on S . We compute,

$$\begin{aligned}
d^*d f &= d^*(\partial_z f dz + \partial_{\bar{z}} f d\bar{z}) \\
&= -d^*(-i\partial_z f dz + i\partial_{\bar{z}} f d\bar{z}) \\
&= -d^*(2i\frac{\partial^2}{\partial z \partial \bar{z}} f dz \wedge d\bar{z}) \\
&= \frac{4}{\lambda^2} \frac{\partial^2}{\partial \bar{z} \partial z} f.
\end{aligned}$$

*

Thus d^*d is, up to a sign, the Laplace-Beltrami operator.

Defns. A form α is said to be co-closed iff $d^*\alpha = 0$, and co-exact there exists an η such that $\alpha = d^*\eta$.

A 1-form α is said to be harmonic iff it is locally of the form $\alpha = df$ w/ f a harmonic function, and holomorphic iff it is locally $\alpha = dh$ w/ h holomorphic.

Lemma 5.2.1. $\alpha = u dz + v d\bar{z}$ is holomorphic iff $v = 0$ and u hol. $\square$

Lemma 5.2.2. A 1-form η is harmonic iff $d\eta = 0 = d^*\eta$. $\square$

Lemma 5.2.3 A 1-form η is harmonic iff it is of the form

$$\eta = \alpha_1 + \bar{\alpha}_2, \quad \alpha_1, \alpha_2 \text{ holomorphic.}$$

A 1-form α is holomorphic iff it is of the form

$$\alpha = \eta + i^* \eta, \quad \eta \text{ harmonic.}$$

We will need the more general notion of meromorphic 1-forms; i.e., one-forms that can be represented locally by

$$\eta(z) = f(z) dz$$

w/ f meromorphic.

We can consider the Laurent expansion about $z_0 = 0$ (in local coordinates)

$$f(z) = \sum_{n=n_0}^{\infty} a_n z^n.$$

The coefficient a_{-1} is called the residue of η at z_0 :

$$\text{Res}_{z_0} \eta := a_{-1}.$$

This number is independent of the choice of local chart, since

$$\text{Res}_{z_0} \eta = \frac{1}{2\pi i} \int_{\gamma} \eta(z)$$

for any γ that is the boundary of a disk B containing z_0 in its interior, w/ η holomorphic on $\bar{B} \setminus \{z_0\}$.

Lemma 5.3.1 Let η be a meromorphic 1-form on a compact Riemann surface S . Let $z_1, \dots, z_m$ be the singularities of η . Then

$$\sum_{j=1}^m \text{Res}_{z_j} \eta = 0.$$

Cor 5.3.1 A meromorphic function f on S has the same number (counting multiplicities) of zeroes and poles.

Classical terminology for Riemann surfaces: A differential form on S is of the

First kind iff η is holomorphic on S

second kind iff η is meromorphic, all of whose residues vanish

third kind iff η is meromorphic, all of whose poles are simple.

Onward toward Riemann-Roch.

Defn 5.4.1 Let S be a Riemann surface. A divisor on S is a locally finite formal linear combination

$$D = \sum s_v z_v \quad (*)$$

with $s_v \in \mathbb{Z}$ and $z_v \in S$.

If S is compact, then D is finite.

The set of divisors on S forms an abelian group, denoted $\text{Div}(S)$.

A divisor D is said to be effective iff $s_v \geq 0$ for all v .

We write $D \geq D'$ if $D - D'$ is effective. Thus $D \geq 0$ means D is effective.

If $g \neq 0$ is a meromorphic function on S , and $z \in S$, then $\text{ord}_z g = k > 0$ if g has a zero of order k at z , and $\text{ord}_z g = -k$ if g has a pole of order k at z . Otherwise $\text{ord}_z g = 0$.

We define the divisor of the meromorphic function $g (\neq 0)$ by

$$(g) = \sum (\text{ord}_z g) z_v$$

If $\eta \neq 0$ is a meromorphic 1-form, we can write $\eta = f dz$ locally and define $\text{ord}_z \eta = \text{ord}_z f$. We thus have $(\eta) = \sum (\text{ord}_z \eta) z_v$, the divisor of η .

Defn. A canonical divisor, always denoted by K , is the divisor (η) of a meromorphic 1-form $\eta \neq 0$ on S .