

3.2. Subspaces

Let V be a vector space, and let S be a subset of V . If S is itself a vector space, then S is called a (vector) subspace of V .

Since all of the elements of V satisfy the eight "A axioms", we need only verify that the elements of S verify the two closure axioms.

Defn. Let S be a nonempty subset of a vector space V . If S satisfies

C1. $\alpha \underline{x} \in S$ whenever $\underline{x} \in S$ and $\alpha \in \mathbb{R}$, and

C2. $\underline{x} + \underline{y} \in S$ whenever $\underline{x}, \underline{y} \in S$,

then S is said to be a (vector) subspace of V .

Remarks.

1. In a vector space V , the sets $\{0\}$ and V are subspaces, called trivial subspaces. All other subspaces are called proper subspaces.

2. For S to be a subspace, it must be nonempty. To verify that S is nonempty, it is usually easiest to show that $0 \in S$.

(0 must be an element of every subspace of V .)

Ex. $S = \{(x_1, x_2, x_3)^T \mid x_1 = x_2\}$

S is nonempty since $(0, 0, 0)^T \in S$.

C1. $(a, a, b) \in S$, $\alpha \in \mathbb{R}$, $\alpha(a, a, b) = (\alpha a, \alpha a, \alpha b) \in S$.

C2. $(a, a, b) + (c, c, d) = (a+c, a+c, b+d) \in S$.

Therefore S is a subspace of $\mathbb{R}^3$.

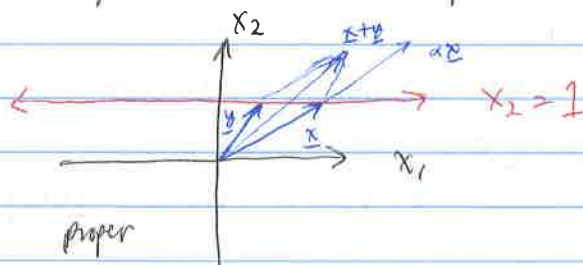
Ex. $S = \left\{ \begin{pmatrix} x \\ 1 \end{pmatrix} \mid x \in \mathbb{R} \right\}$

$$\alpha \begin{pmatrix} x \\ 1 \end{pmatrix} = \begin{pmatrix} \alpha x \\ \alpha \end{pmatrix} \notin S \quad \text{if } \alpha \neq 1.$$

$$\begin{pmatrix} x \\ 1 \end{pmatrix} + \begin{pmatrix} y \\ 1 \end{pmatrix} = \begin{pmatrix} x+y \\ 2 \end{pmatrix} \notin S.$$

So both closure properties ~~both~~ fail to hold. Thus S is not a subspace. (Note: Only 1 needs to fail to get a negative answer.)

This is actually the same example we did last class.



Recall that the n subspaces of $\mathbb{R}^2$ were the lines that passed through the origin.

Ex. $S = \{ A \in \mathbb{R}^{2 \times 2} \mid a_{12} = -a_{21} \}$

Verify that this is a subspace. (of $\mathbb{R}^{2 \times 2}$).

Ex. Let $S = \{ p \in P_n \mid p(0) = 0 \}$.

Show that S is a subspace of P_n .

(RE) Ex. Let $C^n[a, b]$ be the set of all functions f in $C[a, b]$ that have a continuous n^{th} order derivative $f^{(n)} \in C(a, b)$.

Verify that $C^n[a, b]$ is a subspace.

Ex. The function $f(x) = |x|$ is continuous on $[-1, 1]$, but it is not differentiable. Therefore $f \notin C^1[-1, 1]$, and $C^1[-1, 1]$ is a proper subspace of $C[-1, 1]$.

(RE) Show that $g(x) = x|x|$ is in $C[-1, 1]$ and $C^1[-1, 1]$, but not $C^2[-1, 1]$. Therefore C^2 is a proper subspace of both C and C^1 .

Ex. $S = \{f \in C^2[a, b] \mid f''(x) + f(x) = 0, x \in [a, b]\}$.

(RE) Verify that S is a subspace of $C^2[a, b]$.

This means that the set of all solutions on $[a, b]$ of the DE $y'' + y = 0$ forms a vector space.

(RE) Verify that $y_1(x) = \sin(x)$ and $y_2(x) = \cos(x)$ are both in S .

This means that any function of the form

$$f(x) = c_1 \sin(x) + c_2 \cos(x)$$

is in S ; hence also a solution of $y'' + y = 0$.

The Null Space of a Matrix

Let $A \in \mathbb{R}^{m \times n}$, and let $N(A)$ be the set of all solutions of the homogeneous system $A\underline{x} = \underline{0}$.

$$N(A) = \{\underline{x} \in \mathbb{R}^n \mid A\underline{x} = \underline{0}\}.$$

This set is called the null space of A , and always forms a vector subspace of $\mathbb{R}^n$.

Let $\underline{x} \in N(A)$, $\underline{y} \in N(A)$, and $\alpha \in \mathbb{R}$.

C1. $A(\alpha \underline{x}) = \alpha A(\underline{x}) = \alpha \underline{0} = \underline{0}$. So $\alpha \underline{x} \in N(A)$

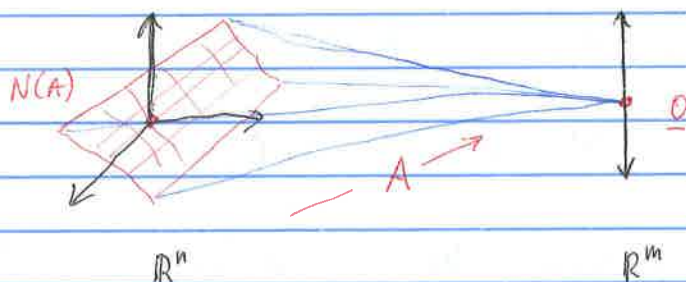
C2. $A(\underline{x} + \underline{y}) = A(\underline{x}) + A(\underline{y}) = \underline{0} + \underline{0} = \underline{0}$ so $\underline{x} + \underline{y} \in N(A)$.

Notice that $\underline{0} \in N(A)$ since the system is homogeneous.

Idea: Think of $A \in \mathbb{R}^{m \times n}$ as a function that takes in a vector $\underline{x} \in \mathbb{R}^n$ and gives back a vector $\underline{b} \in \mathbb{R}^m$.

$$\begin{array}{ccc} \mathbb{R}^n & \xrightarrow{A} & \mathbb{R}^m \\ \underline{x} & \longmapsto & \underline{b} \end{array}$$

The null space of A is the set in $\mathbb{R}^n$ that gets sent to the $\underline{0}$ vector in $\mathbb{R}^m$:



We can't draw higher dimensions, but the schematic picture always looks "like this."

Ex. Let $A = \begin{pmatrix} 1 & 1 & 1 & 0 \\ 2 & 1 & 0 & 1 \end{pmatrix}$. Find $N(A)$.

Use RREF to get $N(A) = \left\{ \alpha \begin{pmatrix} 1 \\ -2 \\ 1 \\ 0 \end{pmatrix} + \beta \begin{pmatrix} -1 \\ 1 \\ 0 \\ 1 \end{pmatrix} \mid \alpha, \beta \in \mathbb{R} \right\}$

The Span of a Set of Vectors

Defn. Let $\underline{x}_1, \underline{x}_2, \dots, \underline{x}_n \in V$. A sum of the form

$$\alpha_1 \underline{x}_1 + \alpha_2 \underline{x}_2 + \dots + \alpha_n \underline{x}_n, \quad \alpha_i \in \mathbb{R}$$

 is called a linear combination of $\underline{x}_1, \underline{x}_2, \dots, \underline{x}_n$.
 The set of all linear combinations of $\underline{x}_1, \underline{x}_2, \dots, \underline{x}_n$ is
 called the span of $\underline{x}_1, \dots, \underline{x}_n$, and we write $\text{Span}\{\underline{x}_1, \underline{x}_2, \dots, \underline{x}_n\}$.

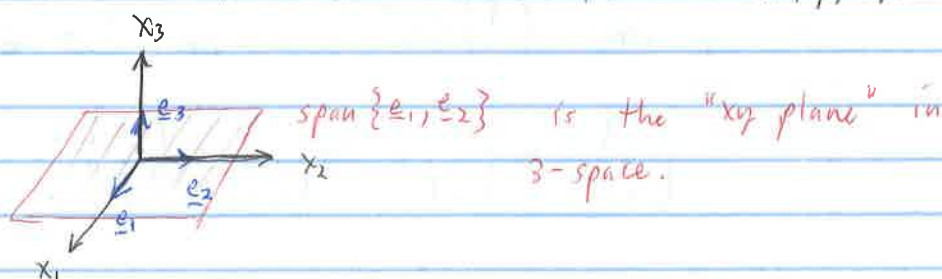
In this lingo, we just found that the null space of A was the span of $(1, -2, 1, 0)^T$ and $(-1, 1, 0, 1)^T$:

$$N(A) = \text{span}\left\{\begin{pmatrix} 1 \\ -2 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ 1 \\ 0 \\ 1 \end{pmatrix}\right\}.$$

Ex. Let $\underline{e}_1, \underline{e}_2 \in \mathbb{R}^3$. The span of $\underline{e}_1$ and $\underline{e}_2$ is

$$\text{Span}\{\underline{e}_1, \underline{e}_2\} = \{\alpha \underline{e}_1 + \beta \underline{e}_2 \mid \alpha, \beta \in \mathbb{R}\}$$

or the set of all vectors that look like $(\alpha, \beta, 0)^T$.



Thm. Let $\underline{x}_1, \underline{x}_2, \dots, \underline{x}_n$ be elements of a vector space V . Then $\text{Span}\{\underline{x}_1, \underline{x}_2, \dots, \underline{x}_n\}$ is a subspace of V .

Proof. VERY STRONGLY RECOMMENDED EXERCISE!
 It's in the book on p. 122, so the RE is to understand it and be able to recreate it in your sleep.

Spanning Sets for a Vector Space

Defn. The set $\{v_1, v_2, \dots, v_n\}$ is a spanning set for V if and only if every vector in V can be written as a linear combination of $v_1, \dots, v_n$.

i.e., iff $\text{Span}\{v_1, \dots, v_n\} = V$.

Ex. Which of the following are spanning sets for $\mathbb{R}^3$?

- | | |
|---|---------------|
| a) $\{e_1, e_2, e_3, (1, 2, 3)^T\}$ | Yes, obvious. |
| b) $\{(1, 1, 1)^T, (1, 1, 0)^T, (1, 0, 0)^T\}$ | Yes |
| c) $\{(1, 0, 1)^T, (0, 1, 0)^T\}$ | No |
| d) $\{(1, 2, 4)^T, (2, 1, 3)^T, (4, -1, 1)^T\}$ | No |

How do we determine this?

Take b) for example.

We ask:

For any vector $\begin{pmatrix} a \\ b \\ c \end{pmatrix} \in \mathbb{R}^3$ can we find x_1, x_2, x_3 such that

$$\begin{pmatrix} a \\ b \\ c \end{pmatrix} = x_1 \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + x_2 \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + x_3 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

In other words, is the system $\begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} a \\ b \\ c \end{pmatrix}$ consistent for any choice of $\begin{pmatrix} a \\ b \\ c \end{pmatrix}$?

We know numerous ways of determining this. If the vectors form a square matrix, then just take the determinant. In this case

$$\det \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} = -1 \neq 0 \quad (-1?)$$

Ex. The vectors $1-x^2$, $x+2$, x^2 span P_3 . Thus if $ax^2 + bx + c$ is a polynomial in P_3 , then it is possible to find scalars α_1 , α_2 , and α_3 such that

$$ax^2 + bx + c = \alpha_1(1-x^2) + \alpha_2(x+2) + \alpha_3 x^2$$

RE. Solve for $\alpha_1, \alpha_2, \alpha_3$ in terms of a, b, c .

Problem 3.2.5 on p. 125 is in the Good Problems 1 packet. Be careful doing this one.

