

3.5. Change of Basis

The standard basis for $\mathbb{R}^2$ is $\{e_1, e_2\}$ so that any vector $\underline{x} \in \mathbb{R}^2$ can be written as

$$\underline{x} = x_1 \underline{e}_1 + x_2 \underline{e}_2$$

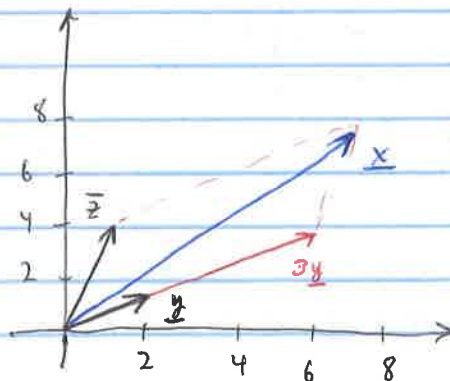
Suppose $\{\underline{y}, \underline{z}\}$ is another basis for $\mathbb{R}^2$. Then $\underline{x}$ can also be represented as

$$\underline{x} = \alpha \underline{y} + \beta \underline{z}$$

The ordered pairs $\underline{x} = (x_1, x_2)^T$ and $\underline{x} = (\alpha, \beta)^T$ are called the coordinates of $\underline{x}$ with respect to the ordered bases $\{\underline{e}_1, \underline{e}_2\}$ and $\{\underline{y}, \underline{z}\}$, respectively.

Ex. Let $\underline{y} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$, $\underline{z} = \begin{pmatrix} 1 \\ 4 \end{pmatrix}$, and $\underline{x} = \begin{pmatrix} 7 \\ 7 \end{pmatrix}$. Then $\underline{x} = 3\underline{y} + \underline{z}$.

The situation is represented geometrically as follows.



The coords of $\underline{x}$ would be $\begin{pmatrix} 3 \\ 1 \end{pmatrix}$ in the (ordered) basis $\{\underline{y}, \underline{z}\}$.

We want to be able to switch between bases.

Change of Coordinates

Consider the standard basis $\{\underline{e}_1, \underline{e}_2\}$ of $\mathbb{R}^2$ and the ordered basis $\{\underline{u}_1, \underline{u}_2\}$ where

$$\underline{u}_1 = \begin{pmatrix} 3 \\ 2 \end{pmatrix} \quad \text{and} \quad \underline{u}_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}.$$

Problem 1. Given a vector $\underline{x} = c_1 \underline{u}_1 + c_2 \underline{u}_2$, find its coordinates wrt the standard basis.

We must write the basis vectors in terms of the standard basis vectors:

$$\underline{u}_1 = 3\underline{e}_1 + 2\underline{e}_2$$

$$\underline{u}_2 = \underline{e}_1 + \underline{e}_2$$

$$\begin{aligned} \text{Then } c_1 \underline{u}_1 + c_2 \underline{u}_2 &= c_1(3\underline{e}_1 + 2\underline{e}_2) + c_2(\underline{e}_1 + \underline{e}_2) \\ &= (3c_1 + c_2)\underline{e}_1 + (2c_1 + c_2)\underline{e}_2 \\ &= \begin{pmatrix} 3c_1 + c_2 \\ 2c_1 + c_2 \end{pmatrix}, \text{ or} \end{aligned}$$

$$\underline{x} = \begin{pmatrix} 3 & 1 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix}$$

Setting $U = (\underline{u}_1, \underline{u}_2) = \begin{pmatrix} 3 & 1 \\ 2 & 1 \end{pmatrix}$, we see that $\underline{x} = U\underline{c}$.

U is called the transition matrix from the ordered basis $\{\underline{u}_1, \underline{u}_2\}$ to the standard basis $\{\underline{e}_1, \underline{e}_2\}$.

Problem 2. Given a vector $\underline{x} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$, find its coords wrt $\{\underline{u}_1, \underline{u}_2\}$.

Now we need the transition matrix from $\{e_1, e_2\}$ to $\{u_1, u_2\}$. Since U is nonsingular (u_1 and u_2 form a basis), then U^{-1} is exactly the matrix we need.

Then wrt $\{u_1, u_2\}$ the vector x is given by

$$c = U^{-1}x.$$

Ex. $u_1 = \begin{pmatrix} 3 \\ 2 \end{pmatrix}$, $u_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$, $x = \begin{pmatrix} 7 \\ 4 \end{pmatrix}$. Find the coords of x wrt $\{u_1, u_2\}$.

$$U = \begin{pmatrix} 3 & 1 \\ 2 & 1 \end{pmatrix} \quad U^{-1} = \begin{pmatrix} 1 & -1 \\ -2 & 3 \end{pmatrix}$$

$$c = \begin{pmatrix} 1 & -1 \\ -2 & 3 \end{pmatrix} \begin{pmatrix} 7 \\ 4 \end{pmatrix} = \begin{pmatrix} 3 \\ -2 \end{pmatrix}$$

$$\text{so } x = 3u_1 - 2u_2.$$

Ex. $b_1 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$, $b_2 = \begin{pmatrix} -2 \\ 3 \end{pmatrix}$, $x = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$

Find the transition matrix from $\{e_1, e_2\}$ to $\{b_1, b_2\}$, then find a coord expression for x wrt $\{b_1, b_2\}$.

$$B = \begin{pmatrix} 1 & -2 \\ -1 & 3 \end{pmatrix} \quad B^{-1} = \begin{pmatrix} 3 & 2 \\ 1 & 1 \end{pmatrix}$$

$$B^{-1}x = \begin{pmatrix} 3 & 2 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 7 \\ 3 \end{pmatrix}$$

$$\text{so } x = 7b_1 + 3b_2.$$

Now consider the problem of changing from one basis $\{v_1, v_2\}$ to another $\{u_1, u_2\}$. Assume the coords for x are known in v -basis. We want to convert to u -basis.

Idea: $\{v_1, v_2\} \xrightarrow{V} \{e_1, e_2\} \xrightarrow{U^{-1}} \{u_1, u_2\}$

$\underbrace{\hspace{10em}}_{U^{-1}V}$

Ex. $v_1 = \begin{pmatrix} 5 \\ 2 \end{pmatrix}, v_2 = \begin{pmatrix} 7 \\ 3 \end{pmatrix}, u_1 = \begin{pmatrix} 3 \\ 2 \end{pmatrix}, u_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

Find the transition matrix $S = U^{-1}V$

$$V = \begin{pmatrix} 5 & 7 \\ 2 & 3 \end{pmatrix} \quad U = \begin{pmatrix} 3 & 1 \\ 2 & 1 \end{pmatrix} \quad U^{-1} = \begin{pmatrix} 1 & -1 \\ -2 & 3 \end{pmatrix}$$

$$S = U^{-1}V = \begin{pmatrix} 1 & -1 \\ -2 & 3 \end{pmatrix} \begin{pmatrix} 5 & 7 \\ 2 & 3 \end{pmatrix} = \begin{pmatrix} 3 & 4 \\ -4 & -5 \end{pmatrix}$$

Ex. Consider the bases $\{1, x, x^2\}$ and $\{1, 2x, 4x^2 - 2\}$. Find the transition matrix:

$$S = \begin{pmatrix} 1 & 0 & -2 \\ 0 & 2 & 0 \\ 0 & 0 & 4 \end{pmatrix} \quad \begin{array}{l} \text{this one is } \{1, 2x, 4x^2 - 2\} \\ \rightarrow \{1, x, x^2\}. \end{array}$$

The transition matrix back is given by

$$S^{-1} = \begin{pmatrix} 1 & 0 & \frac{1}{2} \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{4} \end{pmatrix}$$

You should be able to see this "by inspection" at this point in the course. If not, keep practicing!