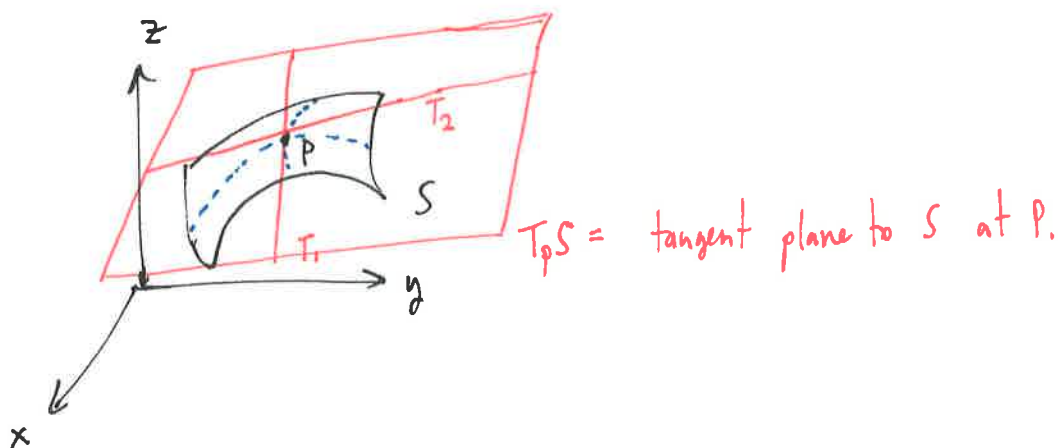


§11.4 Tangent Planes and linear approximations

Consider a surface S that is the graph of $z=f(x,y)$, and suppose f has continuous partial derivatives.

Let $P(x_0, y_0, z_0)$ be a point in $\Gamma(f) = S$.

The tangent lines T_1 to C_1 and T_2 to C_2 from section 11.3 ~~then~~ determine a plane $T_P S$ called the tangent plane to S at P .



Close to P , the surface S looks approximately like the plane $T_P S$, just like in Calc I a curve is locally approximated by the tangent line to a point.

The equation of $T_P S$ is

$$z - z_0 = \partial_x f(x_0, y_0)(x - x_0) + \partial_y f(x_0, y_0)(y - y_0)$$

or

$$z = f(x_0, y_0) + \partial_x f(x_0, y_0)(x - x_0) + \partial_y f(x_0, y_0)(y - y_0)$$

* Very similar to the eqn of a tan line in Calc I.

Ex. Find the tangent plane to $z = 2x^2 + y^2$ at the point $(1, 1, 3)$

$$f(x, y) = 2x^2 + y^2 \quad z_0 = 3$$

$$\partial_x f(x, y) = 4x \quad \partial_x f(x_0, y_0) = 4$$

$$\partial_y f(x, y) = 2y \quad \partial_y f(x_0, y_0) = 2$$

$$\text{So } z = 3 + 4(x-1) + 2(y-1)$$

$$z = 3 + 4x - 4 + 2y - 2$$

$$\boxed{z = 4x + 2y - 3}$$

Linear Approximations

close to P

We can approximate values of $f(x, y) = z$ by the tangent plane $T_P S$. For example, In the last problem

$$L(x, y) = 4x + 2y - 3$$

is the linearization of $f(x, y) = 2x^2 + y^2$ ^(at) near $(1, 1, 3)$.

Close to P $f(x, y) \approx L(x, y)$.

$$\text{For example } f(1.1, 0.95) \approx L(1.1, 0.95) = 4(1.1) + 2(0.95) - 3$$

$$= 4.4 + 1.9 - 3$$

$$= 3.3$$

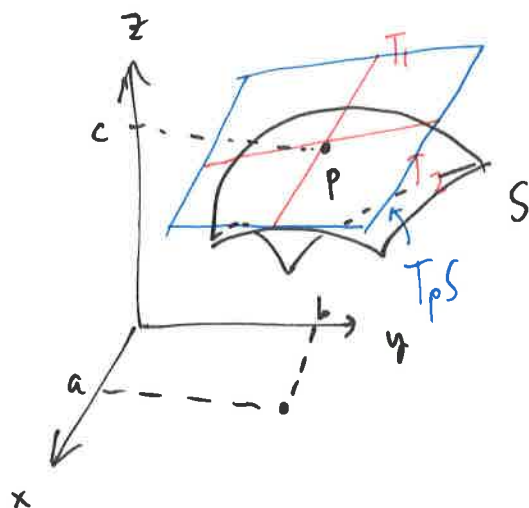
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Plugging into f (and doing more work) we see that

$$f(1.1, 0.95) = 3.3225$$

Recall from last class:

$T_p S$ = the tangent plane to S at the point p



$$p = (a, b, c) \\ c = f(a, b)$$

The tangent plane is given by the equation:

$$z = D_x f(a, b)(x - a) + D_y f(a, b)(y - b) + c$$

This is a real-valued function of x and y called the linearization of f ^(at) ~~near~~ the point (a, b) .

We write

$$L_p(x, y) = D_x f(a, b)(x - a) + D_y f(a, b)(y - b) + f(a, b) \\ \text{or just } L(x, y)$$

Near p , $f(x, y) \approx L(x, y)$.

Now, for a function of two variables

$$\Delta z = f(a + \Delta x, b + \Delta y) - f(a, b)$$

So Δz is the amount of change in the value of f when (x, y) is changed by $(\Delta x, \Delta y)$.

* Now write the defn of differentiable.

This says that f is differentiable at a point if L is a "good" approximation at that point.

Theorem. If $D_x f$ and $D_y f$ exist near (a, b) and are continuous at (a, b) , then f is differentiable at (a, b) .

Ex. Show that $f(x, y) = xe^{xy}$ is differentiable at $(1, 0)$, and find L .
Use it to approx. $f(1.1, -0.1)$.

$$D_x f = xye^{xy} + e^{xy}$$

$$D_x f(1, 0) = 0 + 1 = 1$$

$$D_y f = x^2 e^{xy}$$

$$D_y f(1, 0) = 1$$

Both $D_x f$ and $D_y f$ are continuous. Therefore f is differentiable.

The linearization of f is given by

$$L(x, y) = (x-1) + y + 1 = x + y$$

$$\left\{ \begin{array}{l} L(1.1, -0.1) = 1.1 - 0.1 \\ \quad \quad \quad = 1 \end{array} \right.$$

$$f(1.1, -0.1) \approx 0.98542$$

Ex. Find the linearization of $f(x,y) = \tan^{-1}(x+2y)$ at $(1,0)$

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$$\text{Need } f(1,0) = \arctan(1) = \pi/4$$

$$D_x f(1,0) = \frac{1}{1+1} = 1/2$$

$$D_y f(1,0) = \frac{2}{1+1} = 1$$

$$\text{So } L(x,y) = \frac{1}{2}(x-1) + y + \pi/4$$

Defn. If $z=f(x,y)$, then f is differentiable at (a,b) if Δz can be expressed in the form

$$\Delta z = D_x f(a,b) \Delta x + D_y f(a,b) \Delta y + \varepsilon_1 \Delta x + \varepsilon_2 \Delta y$$

where $\varepsilon_1, \varepsilon_2 \rightarrow 0$ as $(\Delta x, \Delta y) \rightarrow (0,0)$.

Recall from calc I:

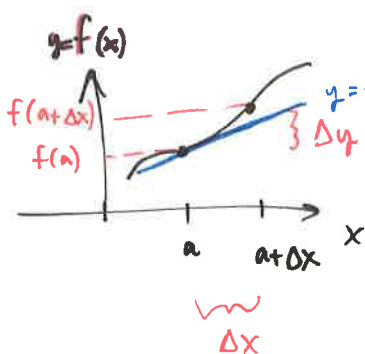
for some small change in x , Δx , the change in y is

$$\Delta y = f(a+\Delta x) - f(a)$$

In Chptr 2: If f is differentiable, then

$$\Delta y = f'(a) \Delta x + \varepsilon \Delta x \quad \text{where } \varepsilon \rightarrow 0 \text{ as } \Delta x \rightarrow 0$$

In the limit we get the differential $dy = f'(a) dx$



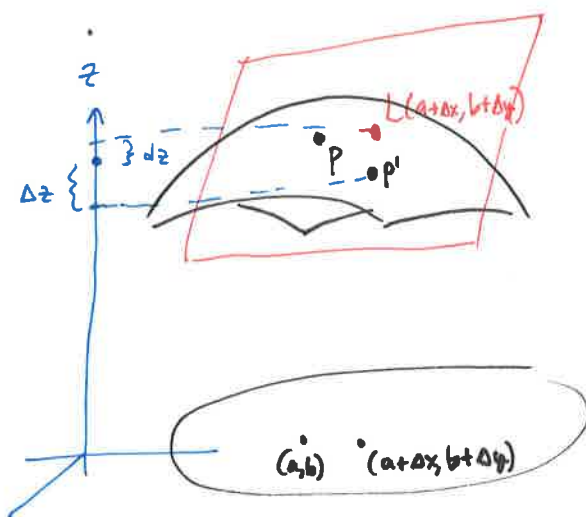
at $x=a+\Delta x$ we get

$$y = f'(a)(a+\Delta x - a) + f(a)$$

Then $\Delta y =$

$$f'(a) \Delta x + f(a) - f(a) = f'(a) \Delta x.$$

Differentials:



Good picture on
p. 622.

Let $dx = \Delta x$ and $dy = \Delta y$ be small changes (increments) in x and y . Then the differential (or total differential) is

$$\left[\begin{aligned} df &= dz = D_x f(x, y) dx + D_y f(x, y) dy \\ &= \frac{\partial z}{\partial x} dx + \frac{\partial z}{\partial y} dy \end{aligned} \right.$$

Suppose we let $dx = \Delta x = x - a$ and $dy = \Delta y = y - b$. Then dz is

$$dz = D_x f(a, b)(x - a) + D_y f(a, b)(y - b)$$

Thus in this notation,

$$f(x, y) \approx f(a, b) + dz \quad (\text{near } (a, b) !)$$

Ex. $z = f(x, y) = x^2 + 3xy - y^2$ Find dz .

$$D_x f = 2x + 3y$$

$$D_y f = 3x - 2y$$

$$dz = (2x + 3y) dx + (3x - 2y) dy$$

Find dz when $(x, y) = (2, 3)$ and $(\Delta x, \Delta y) = (0.05, -0.04)$

$$\begin{aligned} dz &= (2 \cdot 2 + 3 \cdot 3)(0.05) + (3 \cdot 2 - 2 \cdot 3)(-0.04) \\ &= 5.5(0.05) \\ &= 0.65 \end{aligned}$$

Use this to approximate $f(2.05, 2.96)$

$$\begin{aligned} f(2.05, 2.96) &\approx f(2, 3) + dz \\ &= 2^2 + 3(2)(3) - 3^2 + 0.65 \\ &= 4 + 18 - 9 + 0.65 \\ &= \underline{13.65} \end{aligned}$$

Ex. The base radius and height of a right circular cone are measured to be 10 cm and 25 cm respectively, w/ error of up to 0.1 cm possible in each.
Use differentials to estimate the maximum error in the calculated volume.

$$V = \frac{1}{3} \pi r^2 h$$

$$\begin{aligned} dV &= \frac{\partial V}{\partial r} dr + \frac{\partial V}{\partial h} dh = \frac{2}{3} \pi r h dr + \frac{1}{3} \pi r^2 dh \\ &= \frac{2}{3} \pi (10)(25)(0.1) + \frac{1}{3} \pi (10)^2 (0.1) = \frac{1}{3} \pi (0.1) (500 + 100) \\ &= \boxed{20\pi \text{ cm}^3} \end{aligned}$$

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