

Math 511

$[Q's]$ $\begin{bmatrix} 4 \\ 2 \\ 2 \\ 1 \end{bmatrix}$ $\begin{matrix} 2 \\ 0 \\ 0 \\ 2 \end{matrix}$ $\begin{matrix} 1 \\ 1 \\ 1 \\ 1 \end{matrix}$

$$Q = \begin{bmatrix} 4/5 & 4/5 \\ 4/5 & -4/5 \\ 4/5 & -4/5 \\ 4/5 & 4/5 \end{bmatrix} \quad R = \begin{bmatrix} 5 & 2 \\ 0 & 2 \\ 0 & 0 \end{bmatrix}$$

$$q_1 = \frac{1}{5} [4 \ 2 \ 2 \ 1]^T = [4/5 \ 4/5 \ 4/5 \ 4/5]^T$$

q_2 is \mathbb{R}^2 remove parts \perp to q_1

P of \mathbb{R}^2 onto q_1 (projection)

Remember project onto orthonormal basis..

$$v = \langle v, q_1 \rangle q_1 + \langle v, q_2 \rangle q_2 + \dots + \langle v, q_n \rangle q_n$$

$$P = \langle \mathbb{R}^2, q_1 \rangle q_1 = 2 \left[\begin{matrix} 4/5 & 4/5 & 4/5 & 4/5 \end{matrix} \right]^T$$

$$P = \begin{bmatrix} 8/5 & 4/5 & 4/5 & 4/5 \end{bmatrix}^T \quad \mathbb{R}^2 = \begin{bmatrix} 2 & 0 & 0 & 2 \end{bmatrix}^T$$

want the \perp so $\mathbb{R}^2 - P = \begin{bmatrix} 4/5 & -4/5 & -4/5 & 8/5 \end{bmatrix}^T$

$$q_2 = \frac{1}{2} \begin{bmatrix} 4/5 & -4/5 & -4/5 & 8/5 \end{bmatrix}^T$$

$$q_2 = \begin{bmatrix} 1/5 & -4/5 & -4/5 & 4/5 \end{bmatrix}^T$$

q_3 is \mathbb{R}^3 but we remove the \perp to q_1, q_2

P of \mathbb{R}^3 onto q_1, q_2

$$P = \langle X_3, q_{11} \rangle q_{11} + \langle X_3, q_{12} \rangle q_{12}$$

where $X = \begin{bmatrix} 4 & 2 \\ 2 & 0 \\ 2 & 0 \\ 1 & 2 \end{bmatrix}$ $Q = \begin{bmatrix} 4/5 & 4/5 & 0 \\ 4/5 & -4/5 & 1/\sqrt{2} \\ 4/5 & -4/5 & -1/\sqrt{2} \\ 4/5 & 4/5 & 0 \end{bmatrix}$ $R = \begin{bmatrix} 5 & 2 & 1 \\ 0 & 2 & 1 \\ 0 & 0 & \sqrt{2} \end{bmatrix}$

so $P = 1 \cdot [4/5 \ 4/5 \ 4/5 \ 4/5]^T + 1 \cdot [4/5 \ -4/5 \ -4/5 \ 4/5]^T$

$P = [1 \ 0 \ 0 \ 1]^T$ (orth \perp to q_{11}, q_{12})

\rightarrow to get \perp part $X_3 - P = [0 \ 1 \ -1 \ 0]^T$

$q_{13} = \frac{1}{\sqrt{2}} [0 \ 1 \ -1 \ 0]^T =$

check $X = QR$

6.3 $Av = \lambda v$ eigen value / vector

\rightarrow find the eigen value / vector

$(\lambda_1, x_1) \quad (\lambda_2, x_2) \quad \dots \quad (\lambda_k, x_k)$

Mean: $Ax_1 = \lambda_1 x_1$

$Ax_2 = \lambda_2 x_2$

\vdots

$Ax_k = \lambda_k x_k$

left subs: $A [x_1 \ x_2 \ \dots \ x_k]$

right sides: $A [x_1 \ x_2 \ \dots \ x_k]$

$$= [Ax_1 \ Ax_2 \ \dots \ Ax_k]$$

$$= [\lambda_1 x_1 \ \lambda_2 x_2 \ \dots \ \lambda_k x_k]$$

$$= [x_1 \ x_2 \ \dots \ x_k] \begin{bmatrix} \lambda_1 & & 0 \\ & \lambda_2 & \\ 0 & & \lambda_k \end{bmatrix}$$

so we can write this as...

$$A \underbrace{[x_1 \ x_2 \ \dots \ x_k]}_X = \underbrace{[x_1 \ x_2 \ \dots \ x_k]}_X \overbrace{\begin{bmatrix} \lambda_1 & & 0 \\ & \lambda_2 & \\ 0 & & \lambda_k \end{bmatrix}}^D$$

so $\boxed{AX = XD}$

or $X^{-1}AX = D$ \leftarrow diagonalization of A

or $A = (X)(D)(X^{-1})$ \leftarrow factorization of A

Def A is diagonalizable if there is a non-singular matrix X and diagonal matrix D

such that $X^{-1}AX = D$

(we say X diagonalizes A)

$$A \rightarrow \boxed{AX = XD} \quad \left(\begin{array}{l} \text{Solve eigen} \\ \text{value/vector probs for } A \end{array} \right)$$

where $D = \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix}$ eigen values

$$X = [\lambda_1 \ \lambda_2 \ \dots \ \lambda_n]$$

when does X^{-1} exist so we can get to

$$A = XDX^{-1} \text{ or } X^{-1}AX = D$$

(need is n -linearly ind, λ_i)

λ_i $\lambda_1, \dots, \lambda_k$ eigen values and

they are distinct. $\rightarrow \lambda_1, \dots, \lambda_k$ are linearly ind.

ex) $A = \begin{bmatrix} 1 & 2 & 3 \\ 0 & -1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$ $\lambda_1 = 1 \rightarrow \lambda_1 = ?$
 $\lambda_2 = -1 \rightarrow \lambda_2 = ?$
 $\lambda_3 = 2 \rightarrow \lambda_3 = ?$

$$A = XDX^{-1} = \begin{bmatrix} \lambda_1 & \lambda_2 & \lambda_3 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} \lambda_1 & \lambda_2 & \lambda_3 \end{bmatrix}^{-1}$$

How to find λ_i ?

$\lambda_1 = 1$ $\left[\begin{array}{ccc|c} 0 & 2 & 3 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$
 $\lambda_1 = 1$ $\lambda_3 = 0$

$$\lambda_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \quad \lambda_2 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$r_2 = -1 \quad \left[\begin{array}{ccc|c} 2 & 2 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 \end{array} \right] \quad x_1 = -\alpha$$

$$x_2 = \begin{bmatrix} -\alpha \\ \alpha \\ 0 \end{bmatrix}$$

$$x_2 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} \alpha \quad \text{or} \quad \begin{bmatrix} -\sqrt{2} \\ \sqrt{2} \\ 0 \end{bmatrix}$$

$$r_3 = 2 \quad \left[\begin{array}{ccc|c} -1 & 2 & 3 & 0 \\ 0 & -3 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \quad x_1 = 3\alpha$$

$$x_3 = \begin{bmatrix} 3\alpha \\ 0 \\ \alpha \end{bmatrix} \quad \text{or} \quad \begin{bmatrix} 3 \\ 0 \\ 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 0 & -1 & 0 \\ 0 & 0 & 2 \end{bmatrix} = \begin{bmatrix} 1 & -1 & 3 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & -1 & 3 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}^{-1}$$

Note: b/c x_i are not unig

$\rightarrow x$ is not unig

\emptyset is not unig

$$A = \begin{bmatrix} 3 & 1 & -1 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} 3 & 1 & -1 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}^{-1}$$

What if λ_i are not distinct?

→ check that X_i are linearly ind.

ex

$$A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$\lambda_1 = 1$

$$\left[\begin{array}{ccc|c} 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$x_1 = \alpha$ $x_2 = \beta$ $x_3 = 0$

$$X_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$\lambda_2 = 2$

$$\left[\begin{array}{ccc|c} -1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 \end{array} \right]$$

$x_1 = 0$ $x_2 = \alpha$ $x_3 = 0$

$$X_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

$$A \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

X^{-1} does not exist.

$$B = \begin{bmatrix} 1 & 1 & -1 \\ 0 & 2 & -1 \\ 0 & 0 & 1 \end{bmatrix}$$

$\lambda_1 = 1$

$\lambda_2 = 2$

$$\left[\begin{array}{ccc|c} 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$x_1 = \alpha$ $x_2 = \beta$ $x_3 = \gamma$

$x_2 = \beta$

$\lambda_2 = 2$

$X_2 =$

$$\begin{bmatrix} \alpha \\ \beta \\ \beta \end{bmatrix} = \alpha \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + \beta \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$$

$\lambda_1 = 1$ $X_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ $\lambda_3 = 1$ $X_3 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$

for this X^{-1} exists

if X^{-1} does not exist we call
A defective

Why?

$$AX = XD$$

$$\text{or } \boxed{A = XDX^{-1}} \text{ or } X^{-1}AX = D$$

Part B Markov Chain

$$v_0, v_1 = Av_0, v_2 = Av_1, \dots, v_k = Av_{k-1}$$
$$v_2 = A^2 v_0 \quad \boxed{v_k = A^k v_0}$$

v_0, v_1, \dots, v_n : state vectors
Markov chain

$$v_k = A^k v_0 \quad ; \quad \text{Markov process}$$

A : transition matrix

$$\text{if } A = XDX^{-1}$$

$$A^k = (XDX^{-1})^k$$

$$= \underbrace{(XDX^{-1})}_{I} \underbrace{(XDX^{-1})}_{I} \dots \underbrace{(XDX^{-1})}_{I}$$

$$= XD^k X^{-1}$$

$$A^k = X \begin{pmatrix} r_1^k & & 0 \\ & r_2^k & \\ 0 & & r_n^k \end{pmatrix} X^{-1}$$

$$w_0 \quad X D X^{-1}$$

$$A^k x_0 = A \cdot A \cdot \dots \cdot A \cdot v_0 = v_k$$

$$\text{with } X D X^{-1}$$

$$v_k = \underset{\substack{\uparrow \\ \text{eigen} \\ \text{Vectors}}}{X} \begin{bmatrix} \lambda_1^k & & 0 \\ & \ddots & \\ 0 & & \lambda_n^k \end{bmatrix} \underset{\substack{\uparrow \\ \text{eigen} \\ \text{vectors}}}{X^{-1}} v_0$$

(eigen-values)

$$\text{Call } X^{-1} v_0 = w = [w_1 \ w_2 \ \dots \ w_n]$$

$$[X | v_0] \xrightarrow[\text{ops}]{\text{row}} [I | w]$$

$$v_k = X \begin{bmatrix} \lambda_1^k & & 0 \\ & \ddots & \\ 0 & & \lambda_n^k \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \\ \vdots \\ w_n \end{bmatrix}$$

$$v_k = [x_1 \ x_2 \ \dots \ x_n] \begin{bmatrix} \lambda_1^k w_1 \\ \lambda_2^k w_2 \\ \vdots \\ \lambda_n^k w_n \end{bmatrix}$$

$$v_k = \lambda_1^k w_1 x_1 + \lambda_2^k w_2 x_2 + \dots + \lambda_n^k w_n x_n$$

$$v_0, v_1, v_2, \dots$$