NAME:

Math 451 ... Exam 3 - In Class

1) Write function gauss(A) that will take as input a matrix A and perform gaussian elimination with pivoting on the matrix and then return the modified A.

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2) For the Lagrange interpolating polynomial function ...
function [y] = lagrange(x,xc,yc)
   n = length(xc);
   y = 0;
   for k = 1:n
      pt = 1;
      for j = [1:k-1 \ k+1:n]
         pt = pt.*(x - xc(j))./(xc(k) - xc(j));
      end
      t = pt.*yc(k);
      y = y + t;
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end

 \ldots comment on each of the variables, explain what they represent, and explain what each line is doing.

3) Assume you have a function c = linearsolver(A,b) that solves Ac = b, a square systems of equations (number of equations = number of variables). Write a script that will find the coefficients of the least squares fit quadratic polynomial to the data (-1,0), (0,1), (1,1), (2,2), (3,2), (4,0). It will then plot, in the same figure window, the data points with red circles and the quadratic polynomial with a blue curve.

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4) Write the function simpint(f,a,b) for the adaptive quadrature formula using Simpson's rule. Somment your code and explain the technique.

DEr the code

5) In class it was shown that the adaptive quadrature function for Simpson's formula of integration has an improved approximate for the area ...

A = S4 + (S4 - S2)./15;

... find a similar formula for the trapazoidal rule. Show all algebra work.

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(6) Write a set-recursive function called recseq(n) that returns the following sequence as a vector: $a_1 = 2, a_2 = 2$ and for n = 3, 4, 5, ... the recursive formula is $a_n = 2 a_{n-1} + a_{n-2} + 1$.