Fourier Series Methods for Numerical Conformal Mapping of Smooth Domains

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tutorial 2014

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Numerical Conformal Mapping

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Introduction

- Some background
- Numerical preview and gallery

Fourier series methods

- Theodorsen's method (1931)
 - Conjugate harmonic functions
 - Discretization and successive conjugation
- Fornberg's method for the disk (1980)
 - Analyticity conditions
 - Linearization
 - Discretization by N-pt. trig. interp.
- Fornberg-like method for the annulus (1998)
- Multiply connected Fornberg (bounded case, 2009)

Remarks and extra details

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Collaborators

Colleagues: Alan Elcrat (WSU) and John Pfaltzgraff (UNC Chapel Hill)

PhD and MS students: Mark Horn, Noureddine Benchama, Lianju (Julian) Wang, and Everett Kropf

General references

[1.] D. Gaier, *Konstruktive Methoden der konformen Abbildung*, Springer, 1964.

[2.] P. Henrici, *Applied and Computational Complex Analysis, Vol. 3*, Wiley, 1986.

[3.] R.Wegmann, *Methods for Numerical Conformal Mapping*, survey article in Handbook of Complex Analysis: Geometric Function Theory, Vol. 2, R. Kühnau, ed., Elsevier, 2005, pp. 351–477. Includes presentation of Wegmann's Newton-like methods—similar to ours, but Newton updates are found as solutions to linear Riemann-Hilbert problems on circle domains.

Conformal map w = f(z) from disk to target domain

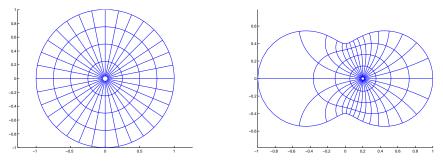


Figure: Fornberg (Fourier series) map from unit disk to interior of an inverted ellipse using 64 Fourier points. $f'(z) \neq 0$, so locally $f(a + h) \approx f(a) + f'(a)h$ and f maps a small circle near z = a to a circle near f(a) magnified by |f'(a)|and rotated by arg f'(a). Therefore curves intersecting at angle θ at a will be mapped to curves intersecting at angle θ at f(a) and the map is angle-preserving or conformal. Existence and uniquesness given by Riemann Mapping Theorem with f(0) and f(1) fixed.

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Boundary correspondence

The boundary Γ of Ω is parametrized by S (e.g., arclength or polar angle), $\Gamma : \gamma(S), 0 \le S \le L, \gamma(0) = \gamma(L)$. If $S = S(\theta)$ or its inverse $\theta(S) = \arg f^{-1}(\gamma(S))$ is known, then the map is known for $z \in D$ or $w \in \Omega$ by the Cauchy Integral Formula,

$$f(z) = rac{1}{2\pi i} \int_{|\zeta|=1} rac{\gamma(\mathcal{S}(heta))}{\zeta - z} d\zeta(heta)$$

or

$$f^{-1}(w) = rac{1}{2\pi i} \int_{\Gamma} rac{e^{i\theta(S)}}{\gamma(S) - w} d\gamma(S).$$

Two classes of methods

- 1. Find $S = S(\theta)$ such that $f(e^{i\theta}) = \gamma(S(\theta))$. We will discuss this case. These methods solve a nonlinear integral equation for $S(\theta)$ by linearly convergent methods of successive approximation (Picard-like iteration) such as Theodorsen's method, or quadratically convergent Newton-like methods such as Fornberg's or Wegmann's methods. Cost: $O(N \log N)$ with FFTs.
- 2. Find $\theta = \theta(S)$ such that $f^{-1}(\gamma(S)) = e^{i\theta(S)}$. These methods solve linear integral equations arising from potential theory for $\theta(S)$ or $\theta'(S)$. Cost: $O(N^2)$ operation counts, but can handle more highly distorted regions.

Two methods for solving nonlinear equations F(X) = 0

1. Successive approximation (Picard), if F(X) = X - G(X),

 $X_{n+1} = G(X_n), \quad X_{n+1} \to X_{soln}, \quad \text{converges if} |G'(X_{soln})| < 1.$

Less work per step, but convergence is linear.

2. Newton's method, solves linear equation at each step

$$X_{n+1} = X_n - F'(X_n)^{-1}F(X_n).$$

More work per step, but convergence is quadratic.

$$\begin{aligned} \text{Taylor series} &= \text{Fourier series} \\ \text{For } |z| < |\zeta| = 1, \zeta = e^{i\theta}, d\zeta = ie^{i\theta} d\theta \\ f(z) &= \frac{1}{2\pi i} \int_{|\zeta|=1} \frac{\gamma(S(\theta))}{\zeta - z} d\zeta \\ &= \frac{1}{2\pi i} \int_{|\zeta|=1} \gamma(S(\theta)) \left(1 + \frac{z}{\zeta} + \left(\frac{z}{\zeta}\right)^2 + \cdots\right) \frac{d\zeta}{\zeta} \\ &= \frac{1}{2\pi} \int_0^{2\pi} \gamma(S(\theta))(1 + ze^{-i\theta} + z^2 e^{-2i\theta} + \cdots) d\theta \\ &= \sum_{k=0}^\infty \left(\frac{1}{2\pi} \int_0^{2\pi} \gamma(S(\theta)) e^{-ik\theta} d\theta\right) z^k \\ &= \sum_{k=0}^\infty a_k z^k, \end{aligned}$$

Taylor coeff. = Fourier coeff. $a_k := \frac{1}{2\pi} \int_0^{2\pi} \gamma(S(\theta)) e^{-ik\theta} d\theta$.

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Applications:

Transplant boundary value problem for Laplace equation from complicated domain to circle domain or model domain and solve using (fast) Fourier/Laurent series or elementary methods. (BVP for biharmonic equation can also be solved by transplanting the analytic functions of the Goursat representation.)

Advantages: *fast methods* and *spectral accuracy* for analytic data and boundaries.

Disdavantages: *Crowding phenomenon*–mapping problem can be *severely ill-conditioned* for distorted domains, e.g., an $L \times 1$ elongated domain has derivatives of order *exp(cL)*.

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Invariance of Laplacian under w = f(z), conformal

$$\Delta_z U = |f'(z)|^2 \Delta_w U,$$

Therefore, since $f'(z) \neq 0$, $\Delta_z U = 0$ iff $\Delta_w U = 0$. (Note that for the *biharmonic equation*, $\Delta_w^2 U = 0$, we have

$$\Delta_w^2 U = |f'(z)|^{-2} \Delta_z \left(|f'(z)|^{-2} \Delta_z U \right) = 0,$$

or

$$\Delta_{z}\left(|f'(z)|^{-2}\Delta_{z}U\right)=0.$$

Therefore, the biharmonic equation does not transplant conformally. However, U = U(w) biharmonic can be written as

$$U = \operatorname{Re}\{\overline{w}\phi(w) + \xi(w)\} = \operatorname{Re}\{\overline{f(z)}\phi(f(z)) + \xi(f(z))\},\$$

where ϕ and ξ are the analytic Goursat functions which transplant analytically.)

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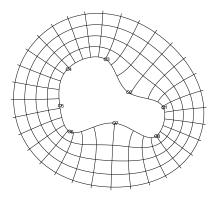


Figure: Fornberg map from exterior of unt disk to exterior of spline

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Simply-connected case: crowding=large distortions=III-conditioning

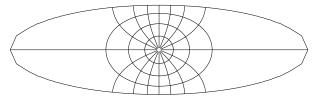


Figure: Fornberg (Fourier series) map from unit disk to interior of ellipse using 1024 Fourier points.

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Map from annulus–D. and Pfaltzgraff (1998)

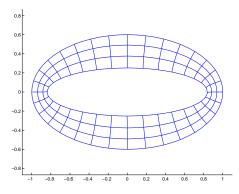


Figure: Doubly connected Fornberg maps annulus $\rho < |z| < 1$ to domain between two ellipses $\alpha = .3, .6$ with N = 64. Normalization fixes one boundary point f(1) to fix rotation of annulus. The inner and outer boundary correspondences $S = S_1(\theta)$ and $S = S_2(\theta)$ along with the unique $\rho(=1/\text{conformal modulus})$ must be computed numerically.

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Interior mult. conn. case–Kropf's MS thesis (2009)

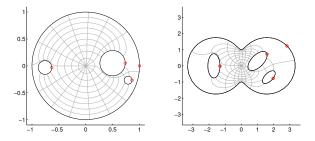
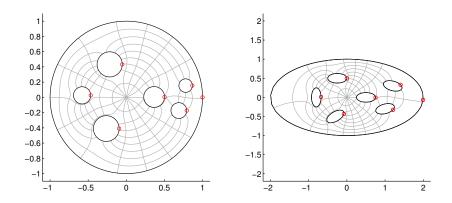


Figure: Outer circle is unit circle. Map normalization fixes f(0) and f(1). m = 4 boundary correspondences and centers and radii of inner circles (unique "conformal moduli") must be computed.



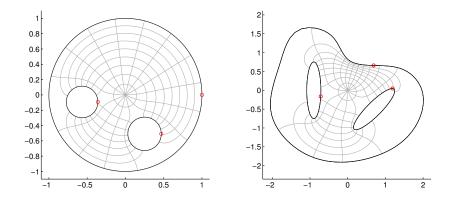
• A target region with m = 7.

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Numerical preview and gallery

Numerical Example

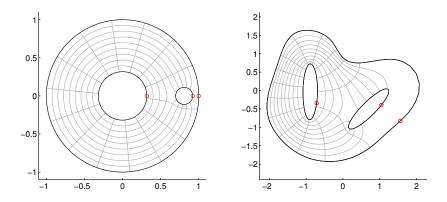


• A target region (on the right) with an outer spline boundary which is parametrized by arclength.

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Numerical preview and gallery

Numerical Example



Annulus with circular holes as a computational domain.

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Exterior mult. conn. case–Benchama's PhD thesis (2003)

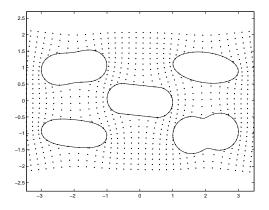
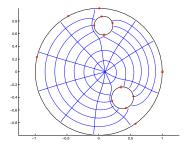


Figure: Fornberg map to the exterior of five curves.

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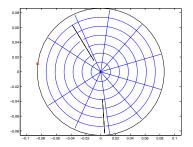


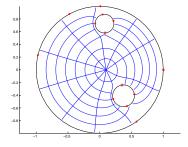
Figure: Infinite product map from circle domain to radial slit disk.

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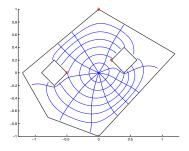


Figure: An orthogonal grid using level lines of map to radial slit disk.

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Conjugate harmonic functions on the disk

Cauchy-Riemann equations in polar coordinates

$$\frac{\partial u}{\partial r} = \frac{1}{r} \frac{\partial v}{\partial \theta}, \qquad \frac{\partial v}{\partial r} = -\frac{1}{r} \frac{\partial u}{\partial \theta}.$$

For $u(r, \theta) = r^n \cos(n\theta)$, $n = \dots, -2, -1, 0, 1, 2, \dots$, the harmonic function conjugate to *u* in the disk is

$$v(r, \theta) = r^n \sin(n\theta) + c$$
, c constant.

This gives

$$u + iv = r^{n}(\cos(n\theta) + i\sin(n\theta)) + ic$$

= $r^{n}e^{in\theta} + ic = (re^{i\theta})^{n} + ic = z^{n} + ic = f(z),$

analytic in $z = re^{i\theta}$. Similarly, if $u(r, \theta) = r^n \sin(n\theta)$, then $v(r, \theta) = -r^n \cos(n\theta) + c$.

Solution of Dirichlet problem on disk

Find $u = u(r, \theta)$ s.t. $\Delta u = 0$ for $0 \le r \le 1$ given (Fourier series for) real boundary data, *h*,

$$u(1,\theta) = h(\theta) = a_0 + \sum_{n=1}^{\infty} a_n \cos n\theta + b_n \sin n\theta.$$

The solution is immediate,

$$u(r,\theta) = a_0 + \sum_{n=1}^{\infty} a_n r^n \cos n\theta + b_n r^n \sin n\theta.$$

For the Dirichlet problem in Ω , we are given boundary values u = b(S)on Γ and transplant to disk, $u(1, \theta) = h(\theta) = b(S(\theta))$.

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Computing the conjugate periodic functions

Define the *conjugation operator* K relating conjugate periodic functions, $\phi(\theta) = u(1, \theta)$ and $\psi(\theta) = v(1, \theta) - b_0$,

$$\phi(\theta) = a_0 + \sum_{n=1}^{\infty} a_n \cos n\theta + b_n \sin n\theta \rightarrow$$

$$\psi(\theta) = K\phi(\theta) := \sum_{n=1}^{\infty} a_n \sin n\theta - b_n \cos n\theta.$$

Therefore, *K* factors as $K = F^{-1}\hat{K}F$, where *F* and F^{-1} are the Fourier transform and it's inverse and

$$\hat{K} = \left\{ egin{array}{c} a_n
ightarrow -b_n \ a_0
ightarrow 0 \ b_n
ightarrow a_n. \end{array}
ight.$$

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MATLAB code for conjugation

Note: for complex $h(\theta) = \sum_{n=-\infty}^{\infty} a_n e^{in\theta}$, since *K* is linear, $Kh(\theta) = \sum_{n=-\infty}^{-1} ia_n e^{in\theta} + \sum_{n=1}^{\infty} -ia_n e^{in\theta}$.

Discretize with N-point trig. interp. and use fft

function Kh = conjug(h) % periodic h sampled at n equidistant pts. n = length(h); n1 = n/2; a = fft(h); a(1) = 0; a(n1 + 1) = 0; k = 2:n1; a(k) = -i*a(k);a(n1 + k) = i*a(n1 + k);

$$Kn = IIII(a);$$

Theodorsen's method

Requires that the boundary Γ be starlike with respect to the origin, i.e.,

$$\Gamma : \gamma(\phi) = \rho(\phi) \boldsymbol{e}^{i\phi}, \mathbf{0} < \rho(\phi), \mathbf{0} \le \phi \le 2\pi.$$

The method finds the *boundary correspondence* $\phi = \phi(\theta)$ by successive conjugation.

Start with *auxiliary function* $h(z) := \log f(z)/z$. Use map normalization f(0) = 0 and f'(0) > 0.

Note that $h(0) = \log f'(0)$ is real and h(z) is analytic in |z| < 1. Next, note that since $f(e^{i\theta}) = \rho(\phi(\theta))e^{i\phi(\theta)}$, we have

$$h(e^{i\theta}) = \log \frac{\rho(\phi(\theta))e^{i\phi(\theta)}}{e^{i\theta}} = \log \rho(\phi(\theta)) + i(\phi(\theta) - \theta)$$

(= $u(1,\theta) + iv(1,\theta)$ above.)

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Theodorsen iteration

Apply conjugation operator K to the real and imaginary parts of

$$h(e^{i\theta}) = \log \rho(\phi(\theta)) + i(\phi(\theta) - \theta)$$

Since $Imh(0) = b_0 = 0$, we have *Theordorsen's equation*,

$$\phi(\theta) - \theta = K[\log \rho(\phi(\theta))]. \tag{1}$$

(-K for the exterior case.) Fixing $\phi(0)$ with $0 \ge \phi(0) < 2\pi$ for uniqueness, solve the iteration,

$$\phi^{(0)}(\theta) = \theta \quad \text{(initial guess)} \\ \phi^{(n+1)}(\theta) - \theta = K[\log \rho(\phi^{(n)}(\theta))].$$

Under suitable conditions on Γ , $\phi^{(n)}(\theta) \rightarrow \phi^{(exact)}(\theta)$, $n \rightarrow \infty$.

K as singular integral operator

$$\mathcal{K}h(heta)=rac{1}{2\pi}\mathcal{P}V\int_{0}^{2\pi}h(au)\cot\left(rac{ heta- au}{2}
ight)d au,$$

where *PV* is the *Cauchy Principal Value* of the integral and $h(\theta)$ is 2π -periodic. (Such singular integral operators are not compact, as we will see.) Define $\delta(\theta) := \phi(\theta) - \theta$. Then $\delta(\theta)$ is 2π -periodic, (whereas, $\phi(\theta)$, of course, is not). Therefore, we actually have *Theodorsen's integral equation* for $\delta = \delta(\theta)$,

$$\delta(heta) = rac{1}{2\pi} PV \int_0^{2\pi} \log(
ho(au + \delta(au)) \cot\left(rac{ heta - au}{2}
ight) d au$$

Note that this is a *nonlinear* integral equation for $\delta(\theta)$ with the nonlinearity entering through the "curve information" $\log(\rho(\tau + \delta(\tau)))$, since *K* itself is a linear operator.

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A useful estimate

Lemma

 $||K||_2 = 1.$

Proof.

$$u(\theta) \sim a_0 + \sum_{n=1}^{\infty} a_n \cos n\theta + b_n \sin n\theta,$$

$$||u||_2^2 = |a_0|^2 + \sum_{n=1}^{\infty} |a_n|^2 + |b_n|^2, \text{ and}$$

$$||Ku||_2^2 = \sum_{n=1}^{\infty} |a_n|^2 + |b_n|^2.$$

Therefore, $||Ku||_2 \le ||u||_2$ and if $a_0 = 0$, then $||Ku||_2 = ||u||_2$. Therefore $||K||_2 = \max_{||u||_2=1} ||Ku||_2 = 1$.

Convergence of Theodorsen

Theorem

Let
$$\epsilon := \sup_{\phi} |\frac{\rho'(\phi)}{\rho(\theta)}|$$
. If $\epsilon < 1$, then $\lim_{n \to \infty} \|\phi(\theta) - \phi^{(n)}(\theta)\|_2 = 0$.

Proof.

From the Theodorsen iteration, we see that

$$\begin{split} \|\phi(\theta) - \phi^{(n+1)}(\theta)\|_{2} &= \|\mathcal{K}[\log \rho(\phi(\theta)) - \log \rho(\phi^{(n)}(\theta))]\|_{2} \\ &\leq \|\log \rho(\phi(\theta)) - \log \rho(\phi^{(n)}(\theta))\|_{2} \\ &= \|\int_{\phi^{(n)}(\theta)}^{\phi(\theta)} \frac{\rho'(\varphi)}{\rho(\varphi)} d\varphi\|_{2} \\ &\leq \epsilon \|\phi(\theta) - \phi^{(n)}(\theta)\|_{2}. \end{split}$$

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geometric condition for convergece of Theodorsen

 ϵ < 1-condition means angle between radial line and normal to curve < $\pi/4,$ i.e., Γ is nearly circular.

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MATLAB code for Theodorsen's method

```
function f = \text{theoint}(n, \text{region}, \text{itmax})
th = 2^{pi^{(0)}}[0:n-1]/n; phi = th; phil = phi;
disp('Iteration no. Error between successive iterates');
f = bdrytheo(region,phi);
for it = 1; itmax
c = log(abs(f));
c = conjug(c);
phi = real(c) + th;
error=max(abs(phi-phil));
phil=phi;
fprintf('
f = bdrytheo(region, phi);
end
```

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Popular test case-the inverted ellipse

The map from the interior of the unit disk to the interior of the ellipse $x^2 + \alpha^2 y^2 = 1$ inverted in the unit circle with minor-to-major axis ratio $0 < \alpha \le 1$ is

$$w=f(z)=\frac{2\alpha z}{1+\alpha-(1-\alpha)z^2}.$$

A starlike wrt 0 parametrization of the boundary is

$$\Gamma: \gamma(\phi) =
ho(\phi) e^{i\phi}, 0 \le \phi \le 2\pi \quad ext{where} \quad
ho(\phi) = \sqrt{1 - (1 - \alpha^2) \sin^2 \phi}.$$

Note: This map can be derived from the Joukowski map f(z) = z + 1/z which maps exteriors of circles to exteriors of ellipses by normalizing properly and rotating.

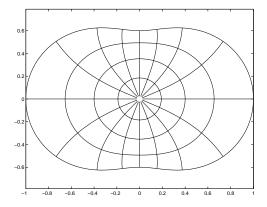


Figure: A target region with an inverted ellipse with $\alpha = .6$. The ϵ -condition is satisfied and Theodorson converged.

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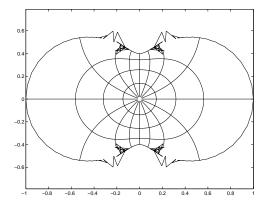


Figure: A target region with an inverted ellipse with $\alpha = .4$. The ϵ -condition is not satisfied and Theodorson failed.

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Conformal map w = f(z) from disk to target domain

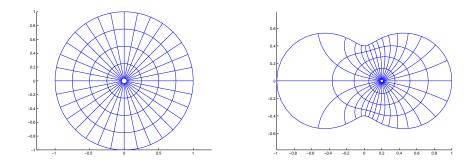


Figure: Fornberg (Fourier series) map from unit disk to interior of an inverted ellipse using 64 Fourier points. Normalization fixes three real parameters: f(0) fixed and f(1) fixed.

Some useful linear operators For $h = h(\theta), 2\pi$ -periodic,

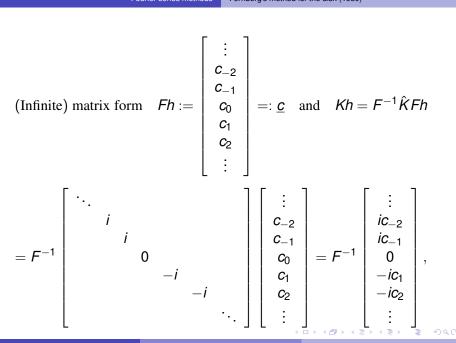
$$Jh(\theta) := \frac{1}{2\pi} \int_0^{2\pi} h(\theta) d\theta = c_0$$
$$P_+h(\theta) := \sum_{k=1}^{\infty} c_k e^{ik\theta}$$
$$P_-h(\theta) := \sum_{k=-\infty}^0 c_k e^{ik\theta}$$

Note that $P_{\pm}^2 = P_{\pm}$ are *projection operators* onto subspaces of $L^2[0, 2\pi]$ whose nonpositive/positive indexed Fourier coefficients 0. Also note

$$P_{+}h = \frac{1}{2}(I + iK - J)h,$$

$$P_{-}h = \frac{1}{2}(I - iK + J)h.$$

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Condition for analytic extension of boundary values

Theorem

A function $h \in Lip(\Gamma)$ can be continued analytically into D^+ (i.e., $f(t) = h(t), t \in \Gamma$) if and only if

$$f(z):=rac{1}{2\pi i}\int\limits_{\Gamma}rac{h(t)}{t-z}dt=0,\quad z\in D^{-},$$

or, equivalently, if

$$\frac{1}{2\pi i}\int\limits_{\Gamma}t^{n}h(t)dt=0,\quad n=0,1,2,\ldots.$$

Proof.

Sufficiency: Cauchy Integral Theorem. Necessity: Sokhotskyi jump relations, $f^+ - f^- = h$.

Condition for unit *D*=disk

Theorem

A function $f \in \text{Lip}(C)$ on the boundary C of the unit disk extends to an analytic function in the interior of the disk with f(0) = 0 if and only if

$$P_{-}f(e^{i\theta})=0.$$

That is, negative indexed coefficients are 0.

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Linearization

Given the *k*th Newton iterate $S = S^k(\theta)$, find correction $U^k(\theta)$, real, such that

$$f(e^{i\theta}) = \gamma(S^k(\theta) + U^k(\theta)) \approx \xi(\theta) + e^{i\beta(\theta)}U(\theta)$$

extends analytically to the interior of the unit disk with f(0) = 0, where $\xi(\theta) = \gamma(S^{(k)}(\theta)), \beta(\theta) = \arg \gamma'(S^{(k)}(\theta))$, and $U(\theta) := |\gamma'(S^{(k)}(\theta)|U^{(k)}(\theta))$ extends analytically to the interior of the unit disk with f(0) = 0. The analyticity condition

$$2P_{-}f = (I - iK + J)f = 0$$

implies that

$$(I-iK+J)e^{i\beta(\theta)}U(\theta)=-2P_{-}\xi(\theta).$$

U real gives

$$(I+R)U = r$$

where $R = \operatorname{Re}(e^{-i\beta}(J-iK)e^{i\beta})$ and $r = -\operatorname{Re}(e^{-i\beta}(I_{+} - iK_{+} + J_{+})\xi)$.

R is a compact operator (Widlund, Wegmann)

$$RU(\theta) := \frac{1}{2\pi} \int_0^{2\pi} \frac{\sin\left(\beta(\phi) - \beta(\theta) + \frac{\theta - \phi}{2}\right)}{\sin\left(\frac{\theta - \phi}{2}\right)} U(\phi) \, d\phi,$$

and for γ sufficiently smooth R^{in} is a symmetric, compact operator on L^2 .

Discretization by *N*-pt. trig. interp. With $E = \text{diag}_j(e^{i\beta(\theta_j)}), j = 0, 1, \dots, N-1$, discretization gives

 $(I_N+R_N)\underline{U}=\underline{r}.$

where the matrix

$$I_N + R_N = \frac{2}{N} \operatorname{Re}(E^H F^H P_N F E)$$

(with $P_N := \text{diag}[1, 0, \dots, 0, 1, \dots, 1]$) is symmetric and pos.(semi)def. with eigenvalues well-grouped around 1 and conjugate gradient converges superlinearly.

Matrix-vector multiplications costs $O(N \log N)$ with FFT.

The Newton update is given by

$$\underline{S}^{(k+1)} = \underline{S}^{(k)} + \underline{U}^{(k)},$$

with $U_0 = 0$ set to fix a boundary point

More details on the matrix-vector formulation

Here $\theta_k = 2\pi k/N$, $0 \le k \le N - 1$, so that

$$\underline{f} = [f_0, \ldots, f_{N-1}]^T \qquad f_j = f(e^{i\theta_j}).$$

For $w = e^{2\pi i/N}$, define the Fourier matrix *F* by

$$F := [w^{-kj}] \qquad 0 \le k, j \le N-1.$$

For $\hat{a}_k := k$ th discrete Fourier coefficients, their *N*-periodicity $\hat{a}_{k+N} = \hat{a}_k$ gives

$$\frac{1}{N}F\underline{f} = \underline{a} = [\hat{a}_0, \dots, \hat{a}_{N/2}, \hat{a}_{-N/2+1}, \dots, \hat{a}_{-1}]^T.$$

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Our discrete analyticity conditions are

$$\hat{a}_k = 0, \qquad k = 0, \ldots, -N/2 + 1.$$

Define

$$E = \operatorname{diag}_{j}[e^{i\beta(\theta_{j})}], \qquad 0 \leq j \leq N-1$$

$$I_{1} = \operatorname{diag}[1, 0, \dots, 0] \qquad I_{2} = \operatorname{diag}[0, 1, \dots, 1]$$

and

$$C = \begin{bmatrix} I_1 & I_2 \end{bmatrix} F E$$

where I_1 and I_2 are $N/2 \times N/2$ matrices. Then the inner Newton system is

$$\underline{f} = \underline{\xi} + E\underline{U}$$

and the discrete analyticity conditions are

$$C\underline{U} = -[I_1 \quad I_2]F\underline{\xi} =: \underline{c}.$$

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To set
$$f(1) = \gamma(0)$$
 requires $S_0 = 0$, and $U_0 = 0$.
Define $\underline{q}^T = [1, 0, ..., 0]$.
Then $U_0 = 0$ is written as $\underline{q}^T \underline{U} = 0$.
Put

$$D = \begin{bmatrix} C \\ \sqrt{N}\underline{q}^{T}/2 \end{bmatrix}, \quad \underline{g} = \begin{bmatrix} \underline{c} \\ 0 \end{bmatrix}.$$

A calculation gives

$$rac{2}{N} \mathrm{Re}(D^H D) = rac{2}{N} \mathrm{Re}(C^H C) + rac{1}{2} rac{qq^T}{q}$$

Finally, since <u>U</u> is real, we obtain

$$\frac{2}{N}\operatorname{Re}(D^{H}D)\underline{U} = \frac{2}{N}\operatorname{Re}(D^{H}\underline{g}).$$
(3)

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It is useful for visualizing our methods to write the matrices in block form,

$$C^{H}C = F^{H}E^{H}\begin{bmatrix} I_{1}\\ I_{2}\end{bmatrix} [I_{1}I_{2}]FE = F^{H}E^{H}\begin{bmatrix} I_{1} & 0\\ 0 & I_{2}\end{bmatrix}FE$$
$$= F^{H}E^{H}\begin{bmatrix} 1\\ 0\\ & \ddots\\ & 0\\ & & 0\\ & & & 1\\ & & & & 1\\ & & & & & 1 \end{bmatrix}FE.$$

Outline



- Some background
- Numerical preview and gallery

Fourier series methods

- Theodorsen's method (1931)
 - Conjugate harmonic functions
 - Discretization and successive conjugation
- Fornberg's method for the disk (1980)
 - Analyticity conditions
 - Linearization
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 - Multiply connected Fornberg (bounded case, 2009)

Remarks and extra details

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Map from annulus–D. and Pfaltzgraff (1998)

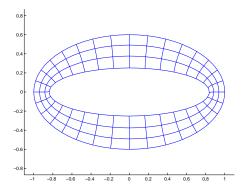


Figure: Doubly connected Fornberg maps annulus $\rho < |z| < 1$ to domain between two ellipses $\alpha = .3, .6$ with N = 64. Normalization fixes one boundary point f(1) to fix rotation of annulus. The inner and outer boundary correspondences $S = S_1(\theta)$ and $S = S_2(\theta)$ along with the unique $\rho(=1/\text{conformal modulus})$ must be computed numerically.

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Analyticty conditions

Let C_1 and C_2 denote the outer and inner boundaries, respectively, of the annulus $\rho < |z| < 1$, and put $C = C_1 - C_2$.

Theorem

A function $h \in Lip(C)$ extends analytically to the annulus $\rho < |z| < 1$ if and only if

$$\int_{C_1} h(z) z^k dz = \int_{C_2} h(z) z^k dz, \quad k \in \mathbf{Z}.$$

If we let

$$h(e^{i\theta}) = \sum_{k=-\infty}^{\infty} a_k e^{ik\theta}$$
 $h(\rho e^{i\theta}) = \sum_{k=-\infty}^{\infty} b_k e^{ik\theta}$

then the above condition becomes $\rho^k a_k = b_k$, $k \in \mathbf{Z}$ or (to prevent overflow)

$$\rho^{k}a_{k} = b_{k}, a_{-k} = \rho^{k}b_{-k}, k = 0, 1, 2, \dots$$

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Mapping problem
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Target region Ω bounded by two smooth curves $\Gamma_1 : \gamma_1(S_1)$ and $\Gamma_2 : \gamma_2(S_2)$.

Problem: Find the *boundary correspondences* $S_1(\theta)$ and $S_2(\theta)$ and the *conformal modulus* ρ such that f(z) is analytic in the annulus $\rho < |z| < 1$ and $f(e^{i\theta}) = \gamma_1(S_1(\theta))$ and $f(\rho e^{i\theta}) = \gamma_2(S_2(\theta))$.

Linearization for Newton-like method

At each Newton step we want to compute corrections $U_1(\theta)$, $U_2(\theta)$, and $\delta \rho$ to $S_1(\theta)$, $S_2(\theta)$, and ρ . With S_j arclength, $\beta_j(\theta) := \arg \gamma'_j(S_j(\theta)), \ \xi_j(\theta) := \gamma_j(S_j(\theta)), \ j = 1, 2, \ \zeta(\theta) := f'(\rho e^{i\theta})e^{i\theta} = -ie^{i\beta_2(\theta)}dS_2(\theta)/d\theta/\rho$, as in [LM] we linearize about S_1, S_2 , and ρ ,

$$egin{aligned} &\gamma_j(\mathcal{S}_j(heta)+\mathcal{U}_j(heta)) &pprox &\gamma_j(\mathcal{S}_j(heta))+\gamma_j'(\mathcal{S}_j(heta))\mathcal{U}_j(heta)), \ j=1,2, \ &f((
ho+\delta
ho)m{e}^{i heta}) &pprox &f(
hom{e}^{i heta})+f'(
hom{e}^{i heta})\delta
hom{e}^{i heta} \end{aligned}$$

giving

1

$$\begin{array}{ll} f(\boldsymbol{e}^{i\theta}) &\approx & \xi_1(\theta) + \boldsymbol{e}^{i\beta_1(\theta)} \boldsymbol{U}_1(\theta) \\ f(\rho \boldsymbol{e}^{i\theta}) &\approx & \xi_2(\theta) + \boldsymbol{e}^{i\beta_2(\theta)} \boldsymbol{U}_2(\theta) - \zeta(\theta)\delta\rho. \end{array}$$

We find U_1 , U_2 , $\delta\rho$ to force these BVs to satisfy the analyticity conditions for the annulus.

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Discrete form of analyticity conditions

N-periodicity of discrete Fourier coefficients $a_{k+N} = a_k$, with N = 2n gives

$$\underline{a} = [a_0, a_1, \dots, a_n, a_{n+1}, \dots, a_{N-1}]^T = [a_0, a_1, \dots, a_n, a_{-n+1}, \dots, a_{-1}]^T.$$

Define the $N \times N$ matrices $P_1 = \text{diag}[1, \rho, \dots, \rho^{n-1}, 1, \dots, 1]$ and $P_2 = -\text{diag}[1, \dots, 1, 1, \rho^{n-1}, \dots, \rho]$. Discrete form of our analyticity conditions (with $a_n = b_n$)

 $P_1\underline{a}+P_2\underline{b}=0.$

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Linear equations With $E_j := \text{diag}_{l=0,...,N-1}[e^{i\beta_j(\theta_l)}], j = 1, 2$, our discrete linearizations become

$$N\underline{a} = F\underline{\xi}_1 + FE_1\underline{U}_1$$
$$N\underline{b} = F\underline{\xi}_2 + FE_2\underline{U}_2 - F\underline{\zeta}\delta\rho.$$

Substituting these linearizations into the discrete analyticity conditions gives our linear system for \underline{U}_1 , \underline{U}_2 , and $\delta\rho$,

$$[C \underline{w}]\underline{U} = P_1 F E_1 \underline{U}_1 + P_2 F E_2 \underline{U}_2 - P_2 F \underline{\zeta} \delta \rho = -P_1 F \underline{\xi}_1 - P_2 F \underline{\xi}_2 =: \underline{c}.$$

where $C = [P_1FE_1 \ P_2FE_2]$ is a complex $N \times 2N$ matrix, $\underline{w} = -P_2F\underline{\zeta}$ is a complex *N*-vector, and

$$\underline{U} = \left[\begin{array}{c} \underline{U}_1 \\ \underline{U}_2 \\ \delta \rho \end{array} \right].$$

This is a system of N complex equations in $2N \pm 1$ real unknowns, $\underline{U}_{3,3,0}$

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Normalization

To satisfy the normalization $f(1) = \gamma_1(0)$, we add the equation $\underline{q}^T \underline{U} = U_0 = \delta := 0$, where $\underline{q}^T = [1, 0, \dots, 0]^T$ is a 2N + 1-vector. We write

$$D = \begin{bmatrix} C & \underline{w} \\ \sqrt{N} & \underline{q}^T/2 \end{bmatrix}, \ \underline{g} := \begin{bmatrix} \underline{c} \\ \delta \end{bmatrix}.$$

and our system now becomes

$$D\underline{U} = \underline{g},$$

a system of *N* complex equations and 1 real equation for the 2N + 1 real unknowns, <u>*U*</u>. Using the "normal equations" and <u>*U*</u> real, we have

$$\frac{2}{N}\operatorname{Re}(D^{H}D)\underline{U} = \underline{r} := \frac{2}{N}\operatorname{Re}(D^{H}\underline{g}).$$

We solve this CG using FFTs.

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System = identity + compact

The above $2N + 1 \times 2N + 1$ -matrix is

$$\frac{2}{N}\operatorname{Re}(D^{H}D) = \begin{bmatrix} A_{11} & A_{12} & \underline{w}_{1} \\ A_{12}^{T} & A_{22} & \underline{w}_{2} \\ \underline{w}_{1}^{H} & \underline{w}_{2}^{H} & 2\underline{w}^{H}\underline{w}/N \end{bmatrix} + \frac{1}{2}\underline{q}\underline{q}^{T}$$

where $A_{ij} = \frac{2}{N} \operatorname{Re}(E_i^H F^H P_i P_j F E_j)$ and $\underline{w}_i = \frac{2}{N} \operatorname{Re}(E_i^H F^H P_i \underline{w})$, i, j = 1, 2. Note that the $2N \times 2N$ matrix containing the analyticity conditions is

$$\frac{2}{N}\operatorname{Re}(C^{H}C) = \left[\begin{array}{cc}A_{11} & A_{12}\\A_{12}^{T} & A_{22}\end{array}\right].$$

We'll see $A_{ii} = I$ +compact, A_{ij} =compact, $i \neq j$ and \underline{w}_i 's are low rank.

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Recall $C = [P_1 F E_1 P_2 F E_2]$. Then, since $P_i^T = P_i$,

$$C^{H}C = \begin{bmatrix} E_{1}^{H}F^{H} & 0\\ 0 & E_{2}^{H}F^{H} \end{bmatrix} \begin{bmatrix} P_{1}^{2} & P_{1}P_{2}\\ P_{2}P_{1} & P_{2}^{2} \end{bmatrix} \begin{bmatrix} FE_{1} & 0\\ 0 & FE_{2} \end{bmatrix}$$

$$\begin{aligned} P_1^2 &= \text{diag}[1, \rho^2, \dots, \rho^{2(n-1)}, 1, \dots, 1], \\ P_2^2 &= \text{diag}[1, \dots, 1, 1, \rho^{2(n-1)}, \dots, \rho^2], \\ P_1P_2 &= \text{diag}[1, \rho, \dots, \rho^{n-1}, 1, \rho^{n-1}, \dots, \rho] \end{aligned}$$

The "1" 's on the diagonals lead to I + R (*R* compact) as in the disk case.

The ρ^{k} 's on the diagonals lead to convolutions with, e.g., $l(\theta) = \rho^{2} e^{i\theta} / (1 - \rho^{2} e^{i\theta}) = \sum_{k=1}^{\infty} \rho^{2k} e^{ik\theta}.$

Therefore, the underlying operator is I + Compact, the eigenvalues cluster around 1, and CG converges superlinearly.

Newton update

$$\underline{S}_{1}^{(k+1)} = \underline{S}_{1}^{(k)} + \underline{U}_{1}^{(k)}
\underline{S}_{2}^{(k+1)} = \underline{S}_{2}^{(k)} + \underline{U}_{2}^{(k)}
\rho^{(k+1)} = \rho^{(k)} + \delta\rho^{(k)}.$$

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Remarks and extra details

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Interior mult. conn. case-Kropf's MS thesis (2009)

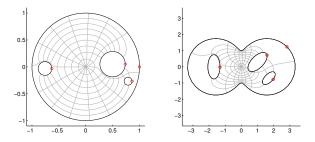
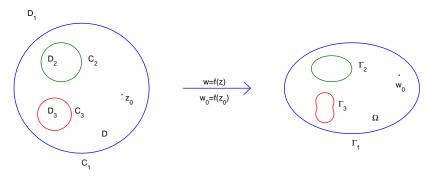


Figure: Outer circle is unit circle. Map normalization fixes f(0) and f(1). m = 4 boundary correspondences and centers and radii of inner circles (unique "conformal moduli") must be computed.

Computational and Target Domains



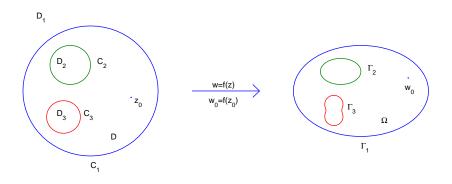
• The boundary of the computational domain *D* is

$$C=C_1-\cdots-C_m,$$

- where m is the connectivity of D
- and C₁ is the unit circle.
- The boundary of the target ("physical") domain Ω is

$$\Gamma = \Gamma_1 - \cdots - \Gamma_m.$$

Boundary Parametrization

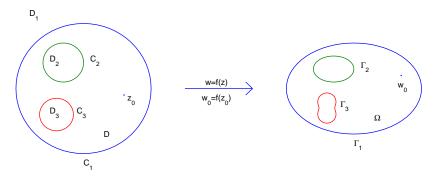


• The target domain boundary will be parametrized, e.g., by arclength,

• *i.e.*,
$$\Gamma : \gamma_1(S_1) - \gamma_2(S_2) - \cdots - \gamma_m(S_m)$$
.

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Computational Goal



• The goal is to compute the conformal map $f: D \rightarrow \Omega$.

To do this we must calculate

the centers c_{ν} and radii ρ_{ν} of the circles C_{ν} , $2 \le \nu \le m$, and

(2) the boundary correspondences $S_{\nu}(\theta)$, where $0 \le \theta \le 2\pi$,

such that $f(c_{\nu} + \rho_{\nu} e^{i\theta}) = \gamma_{\nu}(S_{\nu}(\theta)), 1 \leq \nu \leq m$.

A Newton-like Method

The desired map will be computed using a Newton-like method:

- Segin with an initial guess for the centers c_{ν} and radii ρ_{ν} , and the boundary correspondences $S_{\nu}(\theta)$.
- Using linearized version of the circle map problem, find updates to these values by solving a linear system.
- Apply the updates.
- Keep doing this until the updates found are below some specified value.
- Based on the result of the last Newton iteration, calculate the the map.

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Form of the Map

Theorem

The conformal map described above has the series representation

$$f(z) = \sum_{j=0}^{\infty} a_{1,j} z^{j} + \sum_{\nu=2}^{m} \sum_{j=1}^{\infty} a_{\nu,-j} \left(\frac{\rho_{\nu}}{z - c_{\nu}} \right)^{j},$$

where for $1 \le \nu \le m$ and j > 0 the Fourier coefficients $a_{\nu,j}$ are defined

$$a_{
u,j} := rac{1}{2\pi} \int_0^{2\pi} f(c_
u +
ho_
u e^{i heta}) e^{-ij heta} \, d heta.$$

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Proof of the Form of the Map (part 1)

Proof.

For a point z in D (with z not on the boundary) the Cauchy integral formula gives

$$f(z) = \frac{1}{2\pi i} \int_C \frac{f(\zeta)}{\zeta - z} d\zeta$$

= $\frac{1}{2\pi i} \int_{C_1} \frac{f(\zeta)}{\zeta - z} d\zeta - \sum_{\nu=2}^m \frac{1}{2\pi i} \int_{C_\nu} \frac{f(\zeta)}{\zeta - z} d\zeta.$

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Proof of the Form of the Map (part 2)

Proof.

Note that $\zeta = e^{i\theta} \Rightarrow d\zeta = ie^{i\theta} d\theta$, along with $\frac{|z|}{|\zeta|} < 1$. Expanding the Cauchy kernel around C_1 gives

$$\frac{1}{2\pi i} \int_{C_1} \frac{f(\zeta)}{\zeta - z} d\zeta = \frac{1}{2\pi i} \int_{C_1} f(\zeta) \frac{1}{1 - z/\zeta} \frac{d\zeta}{\zeta}$$
$$= \frac{1}{2\pi i} \int_{C_1} f(\zeta) \sum_{j=0}^{\infty} \left(\frac{z}{\zeta}\right)^j \frac{d\zeta}{\zeta}$$
$$= \sum_{j=0}^{\infty} \left[z^j \frac{1}{2\pi} \int_0^{2\pi} f(e^{i\theta}) e^{-ij\theta} d\theta \right].$$

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Proof of the Form of the Map

(part 3)

Proof.

Additionally $\zeta = c_{\nu} + \rho_{\nu} e^{i\theta} \Rightarrow d\zeta = i \rho_{\nu} e^{i\theta} d\theta$, and $\frac{|\zeta - c_{\nu}|}{|z - c_{\nu}|} < 1$. So on each C_{ν}

$$\begin{aligned} \frac{1}{2\pi i} \int_{C_{\nu}} \frac{f(\zeta)}{\zeta - c_{\nu} - (z - c_{\nu})} d\zeta &= -\frac{1}{2\pi i} \int_{C_{\nu}} f(\zeta) \frac{1}{z - c_{\nu}} \sum_{j=0}^{\infty} \left(\frac{\zeta - c_{\nu}}{z - c_{\nu}} \right)^{j} d\zeta \\ &= -\frac{1}{2\pi} \int_{0}^{2\pi} f(c_{\nu} + \rho_{\nu} e^{i\theta}) \frac{1}{z - c_{\nu}} \sum_{j=0}^{\infty} \left(\frac{\rho_{\nu} e^{i\theta}}{z - c_{\nu}} \right)^{j} \rho_{\nu} e^{i\theta} d\theta \\ &= -\sum_{j=1}^{\infty} \left[\left(\frac{\rho_{\nu}}{z - c_{\nu}} \right)^{j} \frac{1}{2\pi} \int_{0}^{2\pi} f(c_{\nu} + \rho_{\nu} e^{i\theta}) e^{ij\theta} d\theta \right]. \end{aligned}$$

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Analytic Continuation

Theorem

Let *C* be a positively oriented, Lipschitz continuous curve with *D* the region bounded by *C* and D^- the compliment of $D \cup C$. A function $f \in \text{Lip}(C)$ can be continued analytically into *D* if and only if

$$\frac{1}{2\pi i}\int_{C}\frac{f(\zeta)}{\zeta-z}\,d\zeta=0,\quad\forall z\in D^{-}.$$

- A version of this theorem is given by both Henrici and Muskhelishvili.
- It is used here as setup for the next theorem
- where we introduce the conditions for analytic extention (analyticity conditions).

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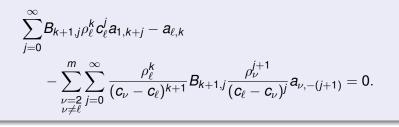
Analyticity Conditions

Theorem

A function $f \in Lip(C)$ extends analytically into D if and only if for all $k \ge 0$

$$a_{1,-(k+1)} - \sum_{
u=2}^{m} \sum_{j=0}^{k} {k \choose j}
ho_{
u}^{j+1} c_{
u}^{k-j} a_{
u,-(j+1)} = 0$$

and



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Note on Analyticity Conditions

For the analyticity conditions we need to define some binomial coefficients.

Definition

For k > 0 and $x, y \in \mathbb{C}$,

$$(x+y)^k = \sum_{j=0}^k \binom{k}{j} x^{k-j} y^j$$
 where $\binom{k}{j} := \frac{k!}{j!(k-j)!}$

Definition

For k > 0 and |z| < 1,

$$rac{1}{(1-z)^k}=\sum_{j=0}^\infty B_{k,j}z^j$$
 where $B_{k,j}:=rac{k(k+1)\cdots(k+j-1)}{j!}.$

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Note on Proof of Analyticity Conditions

The proof involves

- applying the above analytic continuation Theorem for an arbitrary point *z* in each D_1, \ldots, D_m ,
- expanding the function in the appropriate Laurent series, and
- setting the resulting series equal to 0.

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Proof of Analyticity Conditions (Outside C₁)

Proof.

For z in D_1 we have |z| > 1 and $|\zeta|/|z| < 1$ for ζ on any C_1, \ldots, C_m , thus

$$\frac{1}{2\pi i} \int_C \frac{f(\zeta)}{\zeta - z} d\zeta = -\frac{1}{2\pi i} \int_C f(\zeta) \frac{1}{z} \sum_{k=0}^{\infty} \left(\frac{\zeta}{z}\right)^k d\zeta$$
$$= -\sum_{k=0}^{\infty} z^{-k-1} \frac{1}{2\pi i} \int_C f(\zeta) \zeta^k d\zeta = 0.$$

The last integral on the RHS must be zero for all $k \ge 0$.

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Proof of Analyticity Conditions

(Outside C_1)

Proof.

$$0 = \frac{1}{2\pi i} \int_{C} f(\zeta) \zeta^{k} d\zeta = \frac{1}{2\pi i} \int_{C_{1}} f(\zeta) \zeta^{k} d\zeta - \sum_{\nu=2}^{m} \frac{1}{2\pi i} \int_{C_{\nu}} f(\zeta) \zeta^{k} d\zeta$$
$$= \frac{1}{2\pi} \int_{0}^{2\pi} f(e^{i\theta}) e^{i(k+1)\theta} d\theta$$
$$- \sum_{\nu=2}^{m} \sum_{j=0}^{k} {k \choose j} \rho_{\nu}^{j+1} c_{\nu}^{k-j} \frac{1}{2\pi} \int_{0}^{2\pi} f(c_{\nu} + \rho_{\nu} e^{i\theta}) e^{i(j+1)\theta} d\theta$$
$$= a_{1,-(k+1)} - \sum_{\nu=2}^{m} \sum_{j=0}^{k} {k \choose j} \rho_{\nu}^{j+1} c_{\nu}^{k-j} a_{\nu,-(j+1)}.$$

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Proof.

For z in one of D_ℓ we have $|z - c_\ell|/|\zeta - c_\ell| < 1$ for ζ on any C_1, \ldots, C_m , and so

$$0 = \frac{1}{2\pi i} \int_C \frac{f(\zeta)}{\zeta - z} d\zeta = \frac{1}{2\pi i} \int_C \frac{f(\zeta)}{\zeta - c_\ell - (z - c_\ell)} d\zeta$$
$$= \frac{1}{2\pi i} \int_C f(\zeta) \frac{1}{\zeta - c_\ell} \sum_{k=0}^\infty \left(\frac{z - c_\ell}{\zeta - c_\ell}\right)^k d\zeta$$
$$= \sum_{k=0}^\infty (z - c_\ell)^k \frac{1}{2\pi i} \int_C f(\zeta) (\zeta - c_\ell)^{-k-1} d\zeta.$$

Again the last integral on the RHS must be zero for all $k \ge 0$.

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Proof.

Thus around C_1

$$\begin{aligned} \frac{1}{2\pi i} \int_{C_1} f(\zeta) (\zeta - c_\ell)^{-k-1} d\zeta \\ &= \frac{1}{2\pi} \int_0^{2\pi} f(e^{i\theta}) (e^{i\theta} - c_\ell)^{-k-1} e^{i\theta} d\theta \\ &= \sum_{j=0}^\infty B_{k+1,j} c_\ell^j \frac{1}{2\pi} \int_0^{2\pi} f(e^{i\theta}) e^{-i(k+j)\theta} d\theta. \end{aligned}$$

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Proof.

To expand the previous integral we had to apply the binomial theorem.

When integrating around C_1 , $|c_\ell|/|e^{i\theta}| < 1$ and so

$$(e^{i\theta}-c_{\ell})^{-k-1}=\frac{1}{e^{i(k+1)\theta}}\cdot\frac{1}{\left(1-\frac{c_{\ell}}{e^{i\theta}}\right)^{k+1}}=\frac{1}{e^{i(k+1)\theta}}\sum_{j=0}^{\infty}B_{k+1,j}\left(\frac{c_{\ell}}{e^{i\theta}}\right)^{j}.$$

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Proof.

Around C_{ν} , 2 \leq ($\nu \neq \ell$) \leq *m*

$$\begin{split} \frac{1}{2\pi i} \int_{\mathcal{C}_{\nu}} f(\zeta) (\zeta - \mathcal{C}_{\ell})^{-k-1} \, d\zeta \\ &= \frac{1}{2\pi} \int_{0}^{2\pi} f(\mathcal{C}_{\nu} + \rho_{\nu} \mathbf{e}^{i\theta}) (\rho_{\nu} \mathbf{e}^{i\theta} - (\mathcal{C}_{\ell} - \mathcal{C}_{\nu}))^{-k-1} \rho_{\nu} \mathbf{e}^{i\theta} \, d\theta \\ &= \frac{1}{(\mathcal{C}_{\nu} - \mathcal{C}_{\ell})^{k+1}} \sum_{j=0}^{\infty} B_{k+1,j} \frac{\rho_{\nu}^{j+1}}{(\mathcal{C}_{\ell} - \mathcal{C}_{\nu})^{j}} \frac{1}{2\pi} \int_{0}^{2\pi} f(\mathcal{C}_{\nu} + \rho_{\nu} \mathbf{e}^{i\theta}) \mathbf{e}^{i(j+1)\theta} \, d\theta. \end{split}$$

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Proof.

Again the binomial theorem was applied.

Since $\rho_{\nu}/|c_{\ell}-c_{\nu}|<$ 1 around C_{ν} for 2 \leq ($u \neq \ell$) \leq *m*, we have

$$(
ho_{
u} e^{i heta} - (c_{\ell} - c_{
u}))^{-k-1} = rac{1}{(c_{\ell} - c_{
u})^{k+1} (-1)^{k+1} \left(1 - rac{
ho_{
u} e^{i heta}}{c_{\ell} - c_{
u}}
ight)^{k+1}} = rac{1}{(c_{
u} - c_{\ell})^{k+1}} \sum_{j=0}^{\infty} B_{k+1,j} \left(rac{
ho_{
u} e^{i heta}}{c_{\ell} - c_{
u}}
ight)^{j}.$$

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Proof.

And finally, around C_{ℓ}

$$\frac{1}{2\pi i} \int_{C_{\ell}} f(\zeta)(\zeta - c_{\ell})^{-k-1} d\zeta$$

$$= \frac{1}{2\pi} \int_{0}^{2\pi} f(c_{\ell} + \rho_{\ell} e^{i\theta}) \rho_{\ell}^{-k-1} e^{-i(k+1)\theta} \rho_{\ell} e^{i\theta} d\theta$$

$$= \frac{1}{2\pi} \int_{0}^{2\pi} f(c_{\ell} + \rho_{\ell} e^{i\theta}) \rho_{\ell}^{-k} e^{-ik\theta} d\theta.$$

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Proof.

Putting it together,

$$0 = \frac{1}{2\pi i} \int_{C} f(\zeta) (\zeta - c_{\ell})^{-k-1} d\zeta$$

= $\sum_{j=0}^{\infty} B_{k+1,j} \rho_{\ell}^{k} c_{\ell}^{j} a_{1,k+j} - a_{\ell,k}$
 $- \sum_{\substack{\nu=2\\\nu\neq\ell}}^{m} \sum_{j=0}^{\infty} \frac{\rho_{\ell}^{k}}{(c_{\nu} - c_{\ell})^{k+1}} B_{k+1,j} \frac{\rho_{\nu}^{j+1}}{(c_{\ell} - c_{\nu})^{j}} a_{\nu,-(j+1)}.$

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Map Normalization

- The map is normalized by specifying three real conditions.
 - One is given by specifying $f(1) = \gamma_1(0)$.
 - The other two are given by fixing f(z₀) = w₀ for points z₀ ∈ D and w₀ ∈ Ω. This is given by the form of the map previously calculated, *i.e.*

$$w_0 = f(z_0) = \sum_{k=0}^{\infty} a_{1,k} z_0^k + \sum_{\nu=2}^m \sum_{k=1}^{\infty} a_{\nu,-k} \left(\frac{\rho_{\nu}}{z_0 - c_{\nu}} \right)^k$$

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A Newton-like Method

The desired map will be computed using a Newton-like iteration:

- Segin with an initial guess for the centers c_{ν} and radii ρ_{ν} , and the boundary correspondences $S_{\nu}(\theta)$.
- Using a discretized version of the analyticity conditions and normalization conditions, and a linearized version of the circle map problem, find updates to these values by solving a linear system.
- Apply the updates.
- Keep doing this until the updates found are below some specified value.
- Based on the result of the last Newton iteration, calculate the Fourier coefficients to form the map.

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Linearization

We now write $f(c_{\nu} + \rho_{\nu}e^{i\theta}) = \gamma_{\nu}(S_{\nu}(\theta))$ as a linear problem.

• For an initial guess $S_{\nu}(\theta)$ and 2π periodic correction $U_{\nu}(\theta)$,

$$\gamma_{
u}(\mathcal{S}_{
u}(heta) + \mathcal{U}_{
u}(heta)) pprox \gamma_{
u}(\mathcal{S}_{
u}(heta)) + \gamma_{
u}'(\mathcal{S}_{
u}(heta))\mathcal{U}_{
u}(heta).$$

• For an initial guess of c_{ν} and ρ_{ν} with corrections δc_{ν} and $\delta \rho_{\nu}$,

$$egin{aligned} &(f+\delta f)(m{c}_
u+\deltam{c}_
u+(
ho_
u+\delta
ho_
u)m{e}^{i heta})\ &pprox (f+\delta f)(m{c}_
u+
ho_
um{e}^{i heta})+f'(m{c}_
u+
ho_
um{e}^{i heta})(\deltam{c}_
u+\delta
ho_
um{e}^{i heta}). \end{aligned}$$

Setting the RHS of these approximations equal gives

$$(f + \delta f)(\mathbf{c}_{\nu} + \rho_{\nu}\mathbf{e}^{i\theta}) = \gamma_{\nu}(\mathbf{S}_{\nu}(\theta)) + \gamma_{\nu}'(\mathbf{S}_{\nu}(\theta))U_{\nu}(\theta) - f'(\mathbf{c}_{\nu} + \rho_{\nu}\mathbf{e}^{i\theta})(\delta\mathbf{c}_{\nu} + \delta\rho_{\nu}\mathbf{e}^{i\theta}).$$

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Linearization

More concisely

- For convenience define
 - $\xi_{\nu}(\theta) := \gamma_{\nu}(S_{\nu}(\theta)),$
 - $\eta_{\nu}(\theta) := \gamma'_{\nu}(S_{\nu}(\theta))$, and
- The linearization conditions can then be written
 - $(f + \delta f)(e^{i\theta}) = \xi_1(\theta) + \eta_1(\theta)U_1(\theta)$
 - $\bullet (f + \delta f)(\mathbf{c}_{\nu} + \rho_{\nu} \mathbf{e}^{i\theta}) = \xi_{\nu}(\theta) + \eta_{\nu}(\theta) U_{\nu}(\theta) + \zeta_{\nu}(\theta) (\delta \rho_{\nu} + \delta \mathbf{c}_{\nu} \mathbf{e}^{-i\theta})$

for the updates around C_1 and around C_{ν} , $2 \le \nu \le m$, respectively.

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Newton Updates

 After the linear system has been solved, the updates are applied at each step (n) as follows:

•
$$S_{\nu}^{(n)}(\theta) = S_{\nu}^{(n-1)}(\theta) + U_{\nu}^{(n-1)}(\theta)$$

for $1 < \nu < m$. and • $c_{\nu}^{(n)} = c_{\nu}^{(n-1)} + \delta c_{\nu}^{(n-1)}$ • $\rho_{\nu}^{(n)} = \rho_{\nu}^{(n-1)} + \delta \rho_{\nu}^{(n-1)}$

for $2 < \nu < m$.

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N Discrete Fourier Coefficients

- Let N be an even number.
- Let *a*_{1,*k*},..., *a*_{*m*,*k*} now denote the discrete Fourier coefficients.
- The *N*-periodicity of the discrete coefficients, with M = N/2, gives

$$egin{aligned} \underline{a}_{
u} &:= (a_{
u,0}, a_{
u,1}, \dots, a_{
u,N-1})^T \ &= (a_{
u,0}, \dots, a_{
u,M-1}, a_{
u,-M}, \dots, a_{
u,-1})^T \end{aligned}$$

for $1 < \nu < m$.

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N-point Discretization

- Again with M = N/2 we discretize the analyticity and normalization conditions by
 - Imiting both the analyticity and normalization conditions to M terms in each sum expansion, and
 - Imiting the analyticity conditions to M equations.
- This can be done by making $k = 0, \ldots, M 1$ or $k = 1, \ldots, M$ as appropriate. The result is the discrete system of equations ...

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Discrete System of Equations

$$a_{1,-(k+1)} - \sum_{
u=2}^{m} \sum_{j=0}^{k} {k \choose j}
ho_{
u}^{j+1} c_{
u}^{k-j} a_{
u,-(j+1)} = 0,$$

•
$$\sum_{j=0}^{M-1} B_{k+1,j} \rho_{\ell}^{k} c_{\ell}^{j} a_{1,k+j} - a_{\ell,k} \\ - \sum_{\substack{\nu=2\\\nu\neq\ell}}^{m} \sum_{j=0}^{M-1} \frac{\rho_{\ell}^{k}}{(c_{\nu} - c_{\ell})^{k+1}} B_{k+1,j} \frac{\rho_{\nu}^{j+1}}{(c_{\ell} - c_{\nu})^{j}} a_{\nu,-(j+1)} = 0,$$

$$\sum_{j=0}^{M-1} a_{1,j} z_0^j + \sum_{\nu=2}^m \sum_{j=1}^M a_{\nu,-j} \left(\frac{\rho_{\nu}}{z_0 - c_{\nu}} \right)^j = w_0.$$

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Matrix Form

of the Analyticity and Normalization Conditions

The discrete system of equations can be written

$$P\underline{a} = P_1\underline{a}_1 + \dots + P_m\underline{a}_m = \begin{bmatrix} P_1 & \dots & P_m \end{bmatrix} \begin{bmatrix} \underline{a}_1 \\ \vdots \\ \underline{a}_m \end{bmatrix} = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ w_0 \end{bmatrix} := \underline{r}.$$

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Discrete Linearization Conditions

We need to define the vectors and vector functions

$$\bullet \ \underline{\theta} := \frac{2\pi}{N} (0, 1, \dots, N-1)^T,$$

$$\underline{\xi}_{\nu} := \xi_{\nu}(\underline{\theta})$$

• and similarly for $\underline{\eta}_{\nu}, \underline{\zeta}_{\nu}$, and \underline{U}_{ν} .

• If *F* is the discrete Fourier transform matrix, $E_{\nu} := \text{diag}(\underline{\eta}_{\nu})$, $\underline{q} := e^{-i\underline{\theta}}$, and * is the Hadamard product, then the linearization conditions become

•
$$N\underline{a}_1 = F\underline{\xi}_1 + FE_1\underline{U}_1$$
 and

$$\blacktriangleright N\underline{a}_{\nu} = F\overline{\underline{\xi}}_{\nu} + FE_{\nu}\underline{U}_{\nu} + \delta\rho_{\nu}F\underline{\zeta}_{\nu} + \delta c_{\nu}F(\underline{q} * \underline{\zeta}_{\nu}).$$

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New Linear System

- For ease of exposition, assume m = 3 for the rest of this section.
- Combining the discrete system of equations for the analyticity and normalization conditions with the discretized linear conditions gives

 $P_1 F E_1 U_1$

 $+ P_{2}(FE_{2}\underline{U}_{2} + \delta\rho_{2}F\underline{\zeta}_{2} + (\operatorname{Re}\delta c_{2} + i\operatorname{Im}\delta c_{2})F(\underline{q} * \underline{\zeta}_{2}))$ $+ P_{3}(FE_{2}\underline{U}_{3} + \delta\rho_{3}F\underline{\zeta}_{3} + (\operatorname{Re}\delta c_{3} + i\operatorname{Im}\delta c_{3})F(\underline{q} * \underline{\zeta}_{3}))$ $= N\underline{r} - P_{1}F\underline{\xi}_{1} - P_{2}F\underline{\xi}_{2} - P_{3}F\underline{\xi}_{3} := \underline{\tilde{g}}.$

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More Convenience Notation

• Let
$$\underline{w}_{\nu} := P_{\nu}F_{\underline{\zeta}_{\nu}}$$
,
• $\underline{wq}_{\nu} := P_{\nu}F(\underline{q} * \underline{\zeta}_{\nu})$,
• $W := \begin{bmatrix} \underline{w}_2 & \underline{w}_3 & \underline{wq}_2 & \underline{iwq}_2 & \underline{wq}_3 & \underline{iwq}_3 \end{bmatrix}$,
• and of course $P := \begin{bmatrix} P_1 & P_2 & P_3 \end{bmatrix}$.

Also define the real vector <u>U</u> :=

 $\begin{bmatrix} \underline{U}_1^T & \underline{U}_2^T & \underline{U}_3^T & \delta\rho_2 & \delta\rho_3 & \operatorname{Re} \delta c_2 & \operatorname{Im} \delta c_2 & \operatorname{Re} \delta c_3 & \operatorname{Im} \delta c_3 \end{bmatrix}^T.$

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The Matrix \tilde{D}

Combining all of this we now have

$$\tilde{D}\underline{U} := \begin{bmatrix} P_1 & P_2 & P_3 & W \end{bmatrix} \begin{bmatrix} F & 0 & 0 & 0 \\ 0 & F & 0 & 0 \\ 0 & 0 & F & 0 \\ 0 & 0 & 0 & I \end{bmatrix} \begin{bmatrix} E_1 & 0 & 0 & 0 \\ 0 & E_2 & 0 & 0 \\ 0 & 0 & E_3 & 0 \\ 0 & 0 & 0 & I \end{bmatrix} \underline{U} = \underline{\tilde{g}}.$$

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The Matrix D Through normalization

- We add a row to this system to force $U_1(0) = 0$ at every iteration.
- This satisfies the normalization condition $f(1) = \gamma_1(0)$.
- To do this define the vector $\underline{v}^T := (1, 0, \dots, 0)$, and then

$$D := \begin{bmatrix} \tilde{D} \\ rac{\sqrt{N}}{2} \underline{v}^T \end{bmatrix}$$
 and $\underline{g} := \begin{bmatrix} \tilde{g} \\ \overline{0} \end{bmatrix}$.

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The Matrix A

• Taking the "normal equations" and using the fact <u>U</u> is real,

$$\underline{A\underline{U}} := \frac{2}{N} \operatorname{Re}\left(D^{H}D\right)\underline{U} = \frac{2}{N} \operatorname{Re}\left(D^{H}\underline{g}\right) := \underline{\underline{b}}.$$

• This system can now be solved efficiently using the conjugate gradient method.

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The Matrix A Decomposed

Define

•
$$A_{kj} := (2/N) \operatorname{Re} \left(E_k^H F^H P_k^H P_j F E_j \right)$$
 and
• $X_k := (2/N) \operatorname{Re} \left(E_k^H F^H P_k^H W \right)$.

• Then A can be written

$$A = \frac{2}{N} \operatorname{Re} (D^{H}D) = \begin{bmatrix} A_{11} & A_{12} & A_{13} & X_{1} \\ A_{21} & A_{22} & A_{23} & X_{2} \\ A_{31} & A_{32} & A_{33} & X_{3} \\ X_{1}^{T} & X_{2}^{T} & X_{3}^{T} & W^{H}W \end{bmatrix} + \frac{1}{2} \underline{vv}^{T},$$

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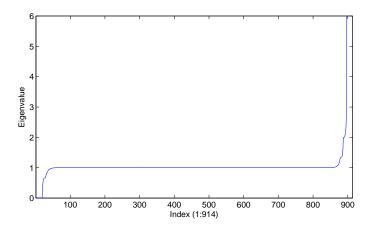
Eigenvalues of A

 To understand the eigenvalues of A it suffices to examine the submatrix

$$\hat{A} = egin{bmatrix} A_{11} & A_{12} & A_{13} \ A_{21} & A_{22} & A_{23} \ A_{31} & A_{32} & A_{33} \end{bmatrix}.$$

- For the eigenvalues:
 - The diagonal entries can be shown to be discretizations of the identity plus a compact operator, and
 - the off-diagonal entries can be shown to be discretizations of a compact operator.
- In effect \hat{A} is a low-rank perturbation of the identity, and the eigenvalues cluster around 1.
- This is the property which makes the conjugate gradient method an efficient solver to use for this problem.

Eigenvalues of A Cluster Around 1

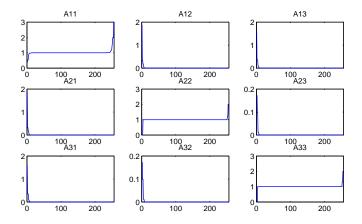


• This map had m = 7 and N = 128.

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Eigenvalues of \hat{A}



• This map had connectivity m = 3 with N = 256.

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Remarks and future work

- The extensions of Fornberg's original method are essentially complete. *I* + *compact* inner systems carry over.
- (The ellipse method was not presented here.)
- The MATLAB codes need to be refined and integrated.
- Further comparisons with Wegmann's methods needs to be done
- An initial version of the code needs to be publicly available.
- Some additional features and improvements are needed:
 - Add grids from slit maps for Green's, Neumann, and Robin functions.
 - Removal of corners with power maps.
 - Code optimization.
 - Automation for initial guesses.
 - Analytic explanation of the nullspace of the matrix A.

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